



# STEP AP209 ed2 Linear Static Structural FEA Handbook

## Volume 2: FEA Steps, Loads and Boundary Conditions for LOTAR EAS Pilot Study #2



# LOTAR

LONG TERM ARCHIVING AND RETRIEVAL

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## Trademark Acknowledgments

NASTRAN is a registered trademark of NASA.

### VERSION LOG

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Updated Draft, added References and Links	JCJ	0.2	4/15/2018
Split Output request and Results into Volume3 (now only Sections 1-6 in Vol.2)	JCJ	0.3	7/16/2018
Incorporated edits recommended by AL	AL/JCJ	0.4	8/27/2018
Incorporated edits recommended by RD	RD/JCJ	0.5	9/24/2018
Remove markups and incorporate final comments per winter 2018 workshop	JCJ	1.0	10/20/2018
Updated source STEP files and text to conform to handbook identifier guidelines	JCJ	1.1	3/25/2019

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## 1 Introduction

This document is a second volume of the AP209 ed2 Linear Static Structural FEA Handbook documenting the finite element load cases and boundary conditions used as source data for the LOTAR International Engineering Analysis and Simulation (EAS) pilot study number two (pilot#2). This study focused on extending implementations of the International Standards Organization (ISO) 10303-209 ed2 (AP209 ed2) Standard, one Part of the 10303 family of Standards commonly known as STEP (Standard for The Exchange of Product data). The document requires at least a cursory understanding of the Finite Element Method, finite element models and analysis (FEM & FEA) and the information technologies involved in applying the AP209 ed2 application protocol. This document can also help the reader focus on those parts of STEP needed to encode FEA information and the documentation resources available to producers, consumers and implementers of this information. Familiarity with the details of Volume 1 of this handbook, covering model definition, is highly recommended; Volume 1 is publicly available at [https://www.cax-if.org/documents\\_cae/HandbookVolume1\\_V2.2\\_CAE-IF.pdf](https://www.cax-if.org/documents_cae/HandbookVolume1_V2.2_CAE-IF.pdf). A condensed version of the introductory sections is repeated here with minor changes from Volume 1.

## 2 Pilot Study Overview

The pilot studies were created to encourage software providers to participate in initial efforts to develop commercial tools capable of converting traditional FEA information, expressed in solver ASCII format, to the AP209 ed2 format. A second goal of the pilot studies was to produce a reference set of AP209 ed2 STEP files that have been validated with the AP209 ed2 EXPRESS schema and have been checked for semantics with respect to the Recommended Practices for AP 209 ed2 10303-209:2014 and the document, Geometric Founding and Associativity in ISO 10303-209, Rev. B, 2/15/2001. A longer term goal is to enable FEA pre and post processors to both read and write AP209ed2 compliant data sets.

The pilot studies provide a small test suite of FEA models and solutions to be translated from a native solver format, in this case NASTRAN, to the STEP AP209 ed2 ASCII file representation (Part 21). These models are prismatic beam models with various linear element types, boundary conditions, load cases, and output requests. The overall geometry for each model is the same and is simple (see Figure 1). This simplicity was intentional to focus the effort on the interpretation of the FEM definitions, constructs and results, not the geometric abstractions related to meshing techniques.

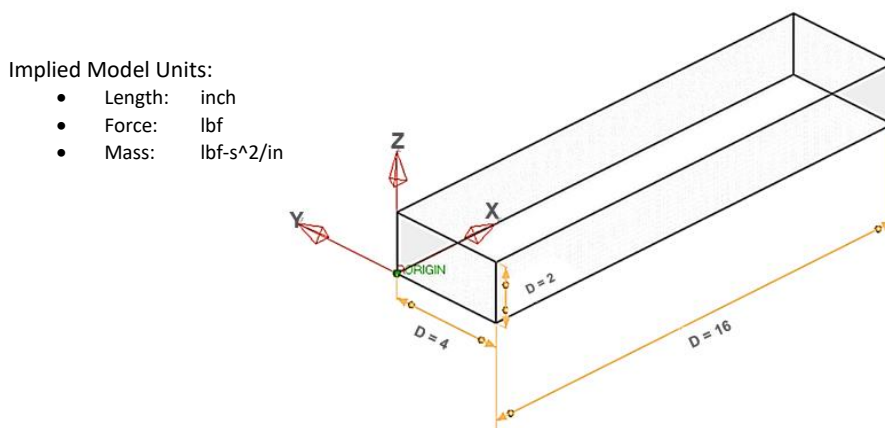


Figure 1 Pilot Model Geometry

Discretization of the geometry to the finite element model domain was accomplished through the abstractions and resulting finite element models shown in Figure 2. The finite element models were exported in NASTRAN bulk data format for use in this pilot study. These models were solved using MSC/NASTRAN V2013.1.0 to generate the requested results.

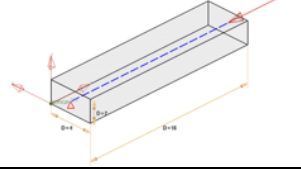
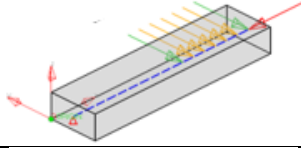
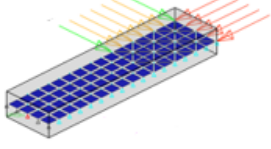
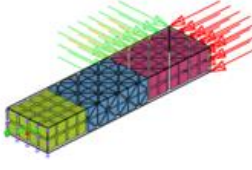
Abstraction - Geometry	NASTRAN Element Type	Pilot Model
1 Dimensional - Line	Linear CROD [Axial Stiffness – 1 DOF]	
1 Dimensional - Line	Linear CBAR [Bending/Axial/Shear – 5 DOF]	
2 Dimensional - Surface	Linear CQUAD4/CTRIA3 [Bending/Membrane/Shear – 5 DOF]	
3 Dimensional - Solid	Linear CHEXA/CPENTA/CTETRA [Bending/Membrane/Shear – 3 DOF]	

Figure 2 Pilot Model Abstractions

Volume 1 of this handbook discussed each pilot model in order and presented the same topics in each sub-section. Where topics were identical (such as using a common isotropic material for all models), a reference to the first occurrence of the topic was presented. This allowed the discussion to focus on the new information unique to each model.

Volume 2 of the handbook differs in how the material is presented to the reader. First, the overall structure of solution controls is discussed, followed by the details of the loads and boundary conditions. Examples from the pilot models are presented to illustrate how the concepts apply to the different model abstractions. Lastly, complete listings of the solver input, excerpts of the solver outputs, and the STEP output are included in the Appendices.

### 3 AP209 Overview

This section introduces several of the information technologies used in working with the STEP standard, and in particular those standards used via AP209 ed2. The reader can use this introduction to locate and explore in detail the topics highlighted herein. This information is a distillation of material found in

similar sections of Volume 1 of this handbook. It is repeated here to ensure these topics are well understood.

AP209, formally known as ISO-10303-209 ed2, Application Protocol: Multidisciplinary Analysis and Design, provides the data structures for the exchange of part and configuration identification with configuration control data, with or without associated 3D part model information. AP209 was developed under the auspices of the International Organization for Standardization (ISO), Technical Committee 184, Sub-Committee 4, and is one of a series of parts comprising the full Standard for the Exchange of Product model data (STEP) standard known as ISO 10303.

### 3.1 STEP Module and Resource Library

Application Protocols such as AP209 ed2 are published in HTML format. All STEP Application Protocols are built from common modules in the SMRL (STEP Module and Resource Library) thus assuring integration and interoperability. The HTML format provides a convenient web browser format to locate definitions for all the entities, types and rules needed for these pilot studies, along with the associated EXPRESS schemas. These documents are copyrighted and published by ISO, so therefore the reader is referred to the ISO web site for access information.

The SMRL contains all the 10303 STEP standards other than the Application Protocols themselves, and consists of the following 10303 Parts:

- Integrated resources series of parts: ISO 10303 Parts 41 to 112;
- Application modules series of parts: ISO 10303 Parts 401 to 499 and 1001 to 1999;
- Application interpreted constructs series of parts: ISO 10303 Parts 501 to 599;
- Logical model of expressions: ISO 13584 Part 20;
- Business object models series of parts: ISO 10303 Parts 3001 to 3099.

Volume 1 of this handbook provides a more complete introduction to the SMRL and is not repeated here.

## 4 AP209 ed2 Data Model Organization

Due to the large scope of the Standard, the AP209 ed2 schema is large and complex. Many views of the data model are presented in the application protocol (AP209 ed2) and recommended practices (RP) documents. In addition to the figures in the RP, Figure 3 shown below illustrates refinements of the RP information to show how the data model can be considered as smaller conceptual topics and how those topics are related to the pilot models.

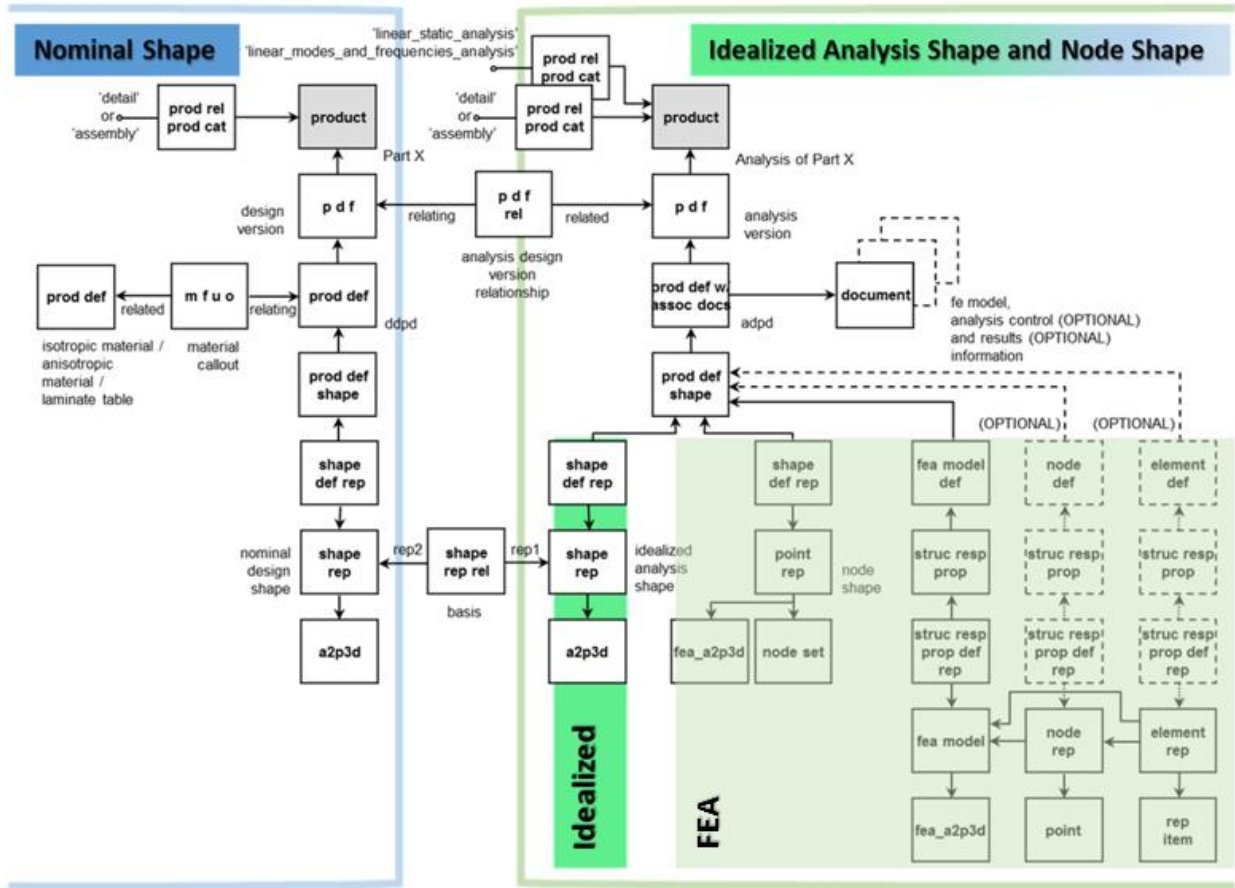


Figure 3 AP209 ed2 Relationship Between Design and Analysis

This view clearly illustrates how the design geometry (nominal shape) is related to the abstracted analysis geometry (idealized analysis shape), the finite element model (node shape) and analysis control and results (optional).

The pilot models in this Handbook use a native solver format (NASTRAN) as the FEM information source and therefore no nominal design or idealized analysis geometry is captured. However, the tools being developed under this pilot study will eventually be required to include the AP209 ed2 constructs that are used to capture the full FEA model definition and solution results. Full FEA model definition includes associativity to nominal design geometry or the idealized analysis geometry used for mesh generation and for mesh and geometry based loads and boundary condition specifications.

Traditionally, FEA solver models do not specify a system of units but are required to be internally consistent. Recent practices have begun to define explicitly a consistent set of units as part of the solver input for FEA model definition. The STEP standard can capture this information when constructing model contexts and associated unit entities. The pilot models do not explicitly specify a system of units, however, there is an implied use of the English inch-pound force-second system due to the existence of recognized material property values. While it may be possible to deduce a likely system of units for a given input file, it is recommended that direct user input define explicitly which system of units applies. How to specify this information for the conversion process is an active area of development and discussion.



#### 4.1 Analysis Product Metadata

The right side of Figure 3 represents the AP209 ed2 analysis product. The figure hides many entities that deal with metadata about the product for the sake of clarity. Figure 4 includes more of these entities and categorizes the metadata of the analysis product; this figure was created from an early STEP file generated for the pilot study using the 1<sup>st</sup> pilot study model.

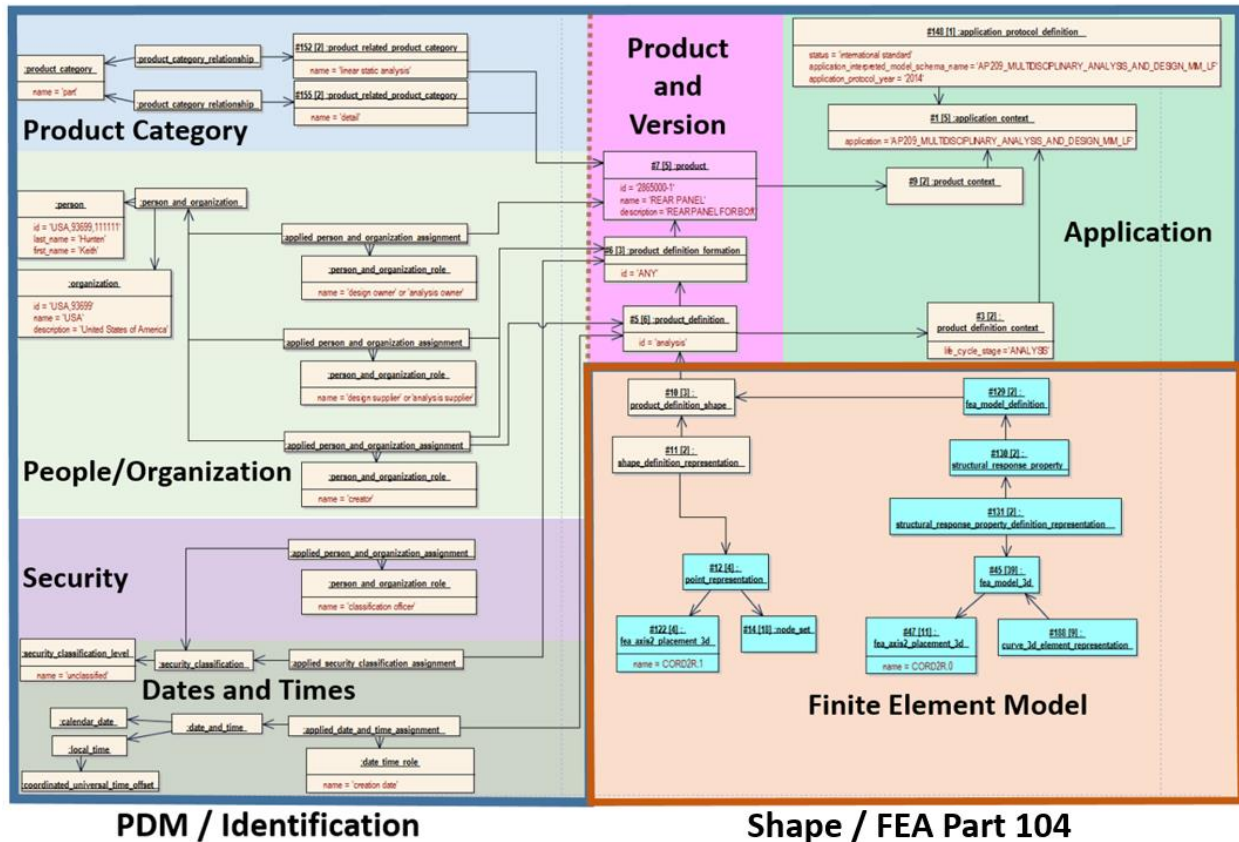


Figure 4 AP209 ed2 Analysis Product Categories

The details of the analysis product model metadata are discussed in Volume 1 of this handbook; the reader is encouraged to review those topics.

This document expands on the lower right corner of Figure 4; it captures the definitions of the finite element pilot models and the resultant control structures not shown in the figure. The contents of this part of the data model are documented in detail in the ISO 10303-104 Integrated application resource: Finite element analysis document (Part 104). Part 104, the associated schema definitions and the Recommended Practice for AP209 ed2 are the primary sources of information needed to map the native solver information (NASTRAN) found in the pilot project input and output files, to the AP209 ed2 data models and produce the familiar Part 21 STEP file representation.

## 5 Analysis Control Structures

The remaining sections in this document discuss the source of FEA results information and the mapping process to AP209 ed2 constructs. These topics are scoped to the following:

- NASTRAN Analysis Control Overview
- Analysis Control Structures – Structures used to describe the operations performed on the FEM
- Steps and States – Describe the specification or requesting of model variables for a single execution of the solution process

### 5.1 NASTRAN Analysis Control Input Overview

The ATS pilot models are simplistic but useful to demonstrate the processes involved in defining the solution controls and interpretation of results. A quick overview of the NASTRAN solution control input information is presented prior to delving into the AP209 ed2 data model mapping and implementation. A complete NASTRAN analysis file is divided into five main input data sections:

- NASTRAN (NASTRAN Command) – Allows specification of NASTRAN execution options
- FMS (File Management Section) – Controls attachment and initialization of database management sets and files
- EXEC (Executive Control Section) – Selects solution sequences, alters and diagnostics
- CASE (Case Control Section) – Specifies load cases, loads, boundary conditions and requests for output formats and output variables
- BULK (Bulk Data Section) – Defines the FEA model along with input data required for the selected solution sequence and subcases

The pilot models use the linear static analysis solution sequence (SOLUTION 101) specified in the Executive Control Section. No further details of the linear static solution sequence are presented in this document, but the details of the Case Control and related Bulk Data Sections and their mapping to AP209 ed2 are discussed. The reader can always explore more detailed explanations of the source information by reviewing the NASTRAN Quick Reference Guide (available online). The documentation is organized by the sections outlined above. The particular version used in this handbook is MSC/NASTRAN Version 2013.1 but any software provider that offers a version of the NASTRAN solver will have similar documentation available.

The pilot models used for this handbook are very similar to the original volume 1 models with the exception of addition output requests or output options specified in the NASTRAN Case Control Section subcases.

The Executive and Case Control template for the ATS1 pilot model is illustrated in Figure 5. The other models have additional subcases but each is structured as shown with similar output requests. Requests that are not supported for a particular element type are ignored. The target for each output request is the 'ALL' string which indicates a request to output the quantity for all applicable nodes or elements.

```

$ Linear Static Analysis
SOL 101
TIME 600
CEND
$
SEALL = ALL
SUPER = ALL
TITLE = Nastran job EAS test case ATS1m5
ECHO = NONE
MAXLINES = 999999999
GPFORCE (PRINT,PUNCH) = ALL
$
SUBCASE 1
  SUBTITLE=subcase1
  SPC = 100
  LOAD = 200
  DISPLACEMENT (PRINT,PUNCH, SORT1, REAL) =ALL
  SPCFORCES (PRINT,PUNCH, SORT1, REAL) =ALL
  STRESS (PRINT,PUNCH, SORT1, REAL, VONMISES, BILIN) =ALL
  STRAIN (PRINT,PUNCH) =ALL
  FORCE (PRINT,PUNCH) =ALL
$
<...Additional Subcases 2 through n...>

```

Figure 5 NASTRAN CASE Control

NASTRAN uses a hierarchical technique to interpret certain output request options. Output options specified for the first subcase STRESS output request are applied to subsequent subcases and to similar output quantities such as STRAIN. Also, output specified above the first subcase definition is applied to all subcases if not overridden. A brief discussion of each of the listed cards is shown in Table 1. Items in gray italics are solver specific control entries and are not currently processed or mapped to any STEP entity.

CARD	Option or Value	Description
SOL	101	Select the linear static solution sequence
<i>TIME</i>	<i>600</i>	<i>Set maximum CPU and I/O time</i>
<i>CEND</i>		<i>Indicates the end of the EXEC section</i>
<i>SEALL</i>	<i>ALL</i>	<i>Superelement ID used in executing the solution sequence</i>
<i>SUPER</i>	<i>ALL</i>	<i>Assigns subcases to superelement or sets of superelements</i>
TITLE		Text label for overall solution
<i>ECHO</i>	<i>NONE</i>	<i>No printout of the input bulk data is selected</i>
<i>MAXLINES</i>	<i>999999999</i>	<i>Maximum number of output lines</i>
GPFORCE	PRINT,PUNCH	Generate printed and punch file output for grid point force balance data
SUBCASE	1	Identifies start of subcase definitions
SUBTITLE	Subcase1	Text label for this subcase
SPC	100	Selects the ID of a set or combination of single point constraint boundary conditions for this subcase

LOAD	200	Selects the ID of a set or combination of applied loads for this subcase
DISPLACEMENT	PRINT,PUNCH	Generate printed and punch file output for node displacements for this subcase
	SORT1, REAL	Organize node output as a deformed shape of the real component of displacement for this subcase
SPCFORCE	PRINT,PUNCH	Generate printed and punch file output for forces of single point constraint (reaction forces for equilibrium)
	SORT1, REAL	Real values sorted by subcase
STRESS	PRINT,PUNCH	Generate printed and punch file output for element stresses
	SORT1, REAL	Real values sorted by subcase
	VONMISES,BILIN	Compute Von Mises stresses at element center and bilinear interpolation to the element corners
STRAIN	PRINT,PUNCH	Generate printed and punch file output for element strains
FORCE	PRINT,PUNCH	Generate printed and punch file output for element forces

*Table 1 NASTRAN Solution Control Card Data*

The PRINT output option generates an ASCII output that is human readable and is formatted for printing on a line printer. The file extension for this file is .f06 and also contains model statistics, summaries and diagnostics information. PUNCH output is also ASCII but is a data-record formatted file that can easily be read by humans or computers. The 'Item Codes' tables located in the NASTRAN Quick Reference Guide define the data record formats for this file. Additional binary output files (.op2, .xdb or .h5) can be requested that contain NASTRAN data blocks used in the solution sequence. Reading a binary file is the preferred method to obtain result data for all but trivial sized FEA models. For the pilot studies, several formats are provided.

The sections that follow present how each quantity and option is implemented in the AP209 ed2 data model for the categories of elements (curve, surface or volume) used in the pilot studies.

## 5.2 AP209 ed2 Analysis Control Structures

The AP209 ed2 control structures represent the operations that are specified and performed on the **fea\_model\_3d** entity. Also, they relate the analysis results to the appropriate input controls. The basic control and result structure is presented in the AP209 ed2 Recommended Practices document and is repeated here as Figure 6.

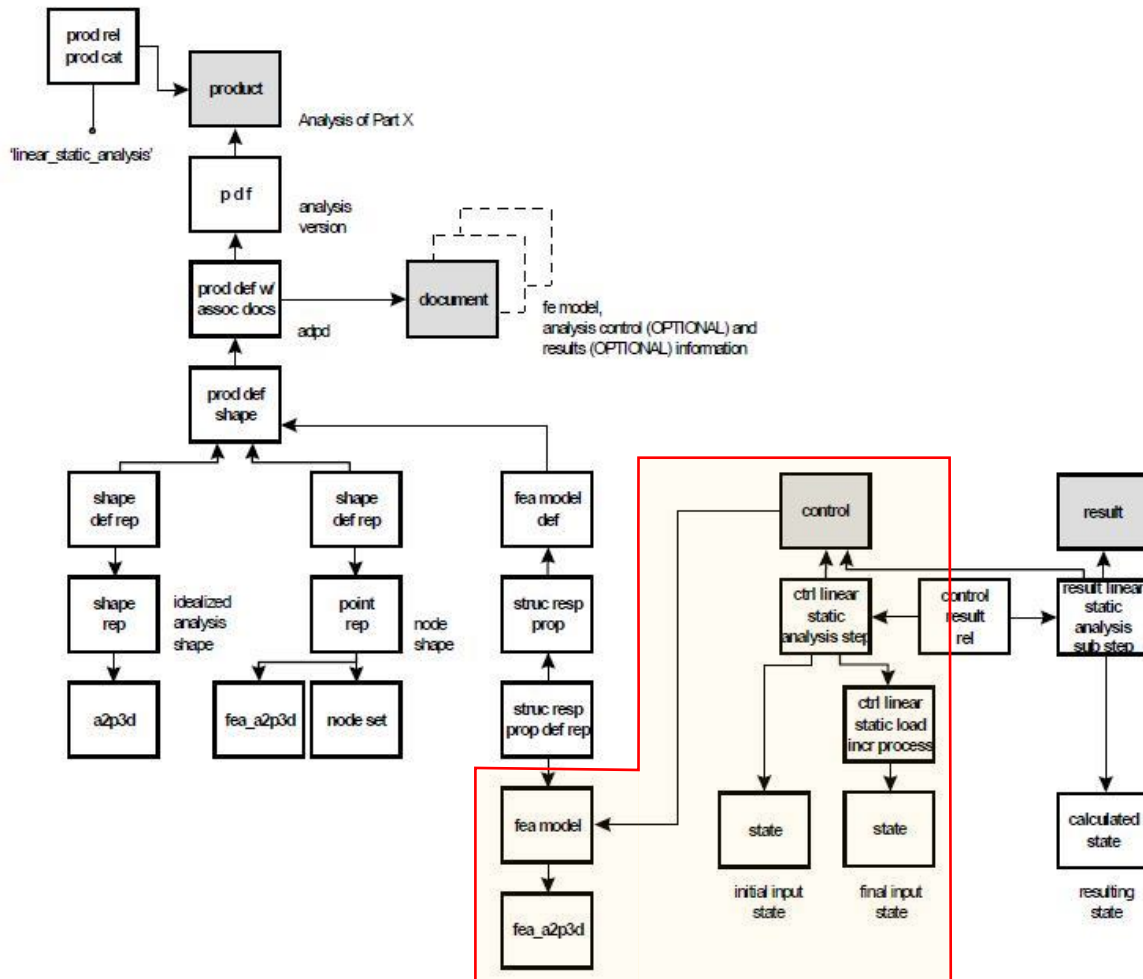


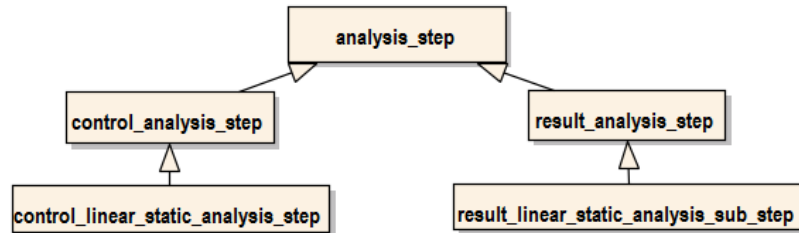
Figure 6 Linear Static Analysis - Control Structures

This document focuses on the shaded area which shows the top level relationship of the control to the **fea\_model** (superclass of **fea\_model\_3d**). The **fea\_model** is the top level entity for the definition of the FEA model mesh, physical properties and material properties while the control structures define load cases, boundary conditions, loads and links to results. Refer to Volume 1 for a discussion of the **fea\_model** and also the entities outside the shaded area.

Below the control entities in Figure 6 are entities that are specializations of the EXPRESS **analysis\_step** class. These subclasses represent the FEA load case or subcase concept. A new set of the **control\_linear\_static\_analysis\_step** entities will be instantiated for each subcase. If no results are being mapped to AP209 ed2, then only the **control\_linear\_static\_analysis\_step** and related entities will be

present. If only the model definition (mesh) without loads and boundary conditions are being processed, then no control entity will be required.

Figure 7 is the class inheritance diagram for the **analysis\_step** subclasses followed by the flattened EXPRESS schema definitions in Figure 8. Through the inheritance mechanism, it shows how the full set of attributes for each subclass are built up to support the control entity structure defined in Figure 6. Note that each subclass references 'to' the top level control which forms a 'many-to-one' relationship between the analysis steps and the top level control.



*Figure 7 Analysis\_step Class Inheritance Diagram*

The **control\_result\_relationship** class definition is also included in Figure 8. Instances of this class allow results steps to be associated to the appropriate control steps. Note that this is a 'one-to-one' relationship necessitating a separate instance for each combination of **control\_analysis\_step** and **result\_analysis\_step**.

A basic understanding of the EXPRESS schema language for class and type definitions was discussed in Volume 1 of this handbook and is not repeated. Again, the reader is encouraged to review the AP209 ed2 standard and the Recommended Practices document which discusses these entities in detail. Red text are the formal names and the blue text highlights relevant attributes for review.

```

ENTITY control_linear_static_analysis_step;
  ENTITY analysis_step;
    analysis_control : control;
  ENTITY control_analysis_step;
    step_id : IDENTIFIER;
    sequence : INTEGER;
    initial_state : state;
    description : TEXT;
  ENTITY control_linear_static_analysis_step;
    process : control_linear_static_load_increment_process;
END_ENTITY;

ENTITY control_linear_static_load_increment_process;
  ENTITY control_process;
    process_id : IDENTIFIER;
    description : TEXT;
  ENTITY control_linear_static_load_increment_process;
    final_input_state : state;
END_ENTITY;

ENTITY control_result_relationship;
  control : control_analysis_step;
  result : result_analysis_step;
END_ENTITY;

ENTITY specified_state;
  ENTITY state;
    state_id : IDENTIFIER;
    description : TEXT;
  ENTITY specified_state;
END_ENTITY;

```

Figure 8 EXPRESS Schema for Control Step and Load Increment Process

These schema definitions also contain attributes that refer to several other entity classes. The **control\_step** references a **control\_linear\_static\_load\_increment\_process**, which in turn, refers to a single **state** entity through the **final\_input\_state** attribute. These **state** entities function as top level collectors of all the information defining each subcase or step. A brief definition of the collector **state** entities used in Figure 6 is presented in Figure 9 along with an illustration of these states for a cantilevered beam.



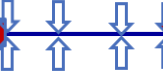
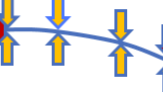
<b>Initial input state</b>	The initial values of the solution variables and related field variables (can be values from a prior step)	
<b>Final input state</b>	The boundary conditions and applied loads that are to be balanced by reaction forces and internal forces of the model to achieve static equilibrium	
<b>Output request state</b>	Requests specific output quantities. A single template instance of each result state with unspecified values. Relates directly to an analysis step	
<b>Resulting state</b>	The calculated values of the solution variables and related field variables after equilibrium has been achieved at the end of the solution process	

Figure 9 Interpretation of State Collectors for a Control\_Step

These collector **state**(s) are referenced ‘from’ an analysis step or process entity through a simple entity reference; therefore, there can only be a single instance for each analysis step. In general, **state** entities and its subclasses can be related to each other through use of **state\_relationship** entities that have

attributes representing the **relating** and the **related** state entities. Through use of these entities, complex hierarchical data structures can be constructed to represent the collections of FEA information associated to a load step or subcase. The **relating** state is the parent or aggregator while the **related** state is the child or item being aggregated.

Figure 10 is taken from the Recommended Practice document for AP209 ed2 to illustrate use of the **state\_relationships** in relating the top level collector **state** and the lower level **specified\_states** in a simple tree structure under the process entities. **Specified\_states** are a sub-class of the **state** class but have no additional attributes and can be referenced by the **state\_relationships**. This type of sub-classing is used to distinguish instances of the specialized sub-class from other entity classes that also inherit from the **state** super-class. Instances of **specified\_state** can be used for the top level aggregator.

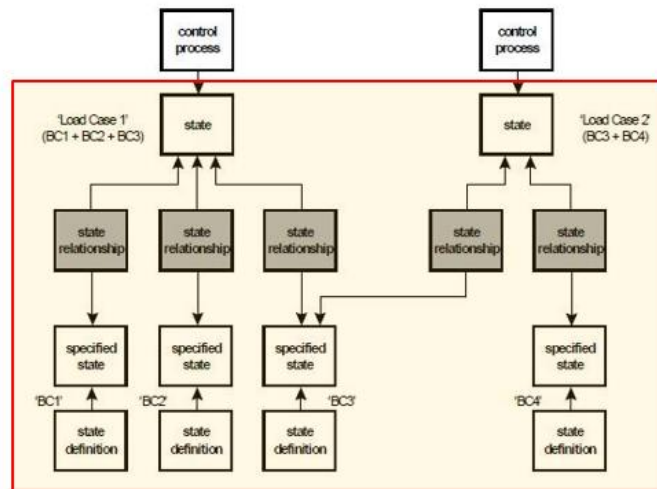


Figure 10 Simple Tree Structure of States

One concept that often causes confusion is the use of the terms ‘initial’ and ‘final’ in the context of the control inputs. Do not confuse ‘initial’ with the applied loads or specified boundary conditions. ‘Initial’ refers to initial values of solution variables known from a prior step while ‘final’ refers to the set of inputs that are the specified part of the final set of solution variables at equilibrium. Details of these control structures are presented in the next section.

### 5.3 NASTRAN Case Control Specified as Analysis Steps

The AP209 ed2 control structures are used to capture the information specified in the NASTRAN Case Control Section. Specifically, the subcase definitions in a NASTRAN solver deck are mapped directly to **control\_linear\_static\_analysis\_step** and the related process and state entities. These top level control, process and state entities together provide attributes to capture the semantics of the subcase information. Each of the diagrams presented in this handbook follows this aggregate view of the subcase (step+process+state).

There is limited guidance in the recommended practice on how to capture identifiers for this information; participants in the pilot study chose different mappings which led to problems interpreting each other’s STEP output as well as problems identifying and visualizing the loads and boundary conditions for each subcase. Specifically, for each **control** entity, the



**control\_linear\_static\_analysis\_step.step\_id** must be populated with a unique subcase identifier. In NASTRAN, this refers to the unique integer subcase id. Additionally, the optional NASTRAN title, subtitle, and label for each subcase should map to the description attributes for the step, process and top level state instance. Figure 11 illustrates guidance for identifying the subcase id and highlights the aggregate view of an FEA subcase. The sequence attribute provides an index for sorting the steps into the solver order and should be used for the **step\_id** when no other value is provided. The sequence attribute also has a uniqueness requirement.

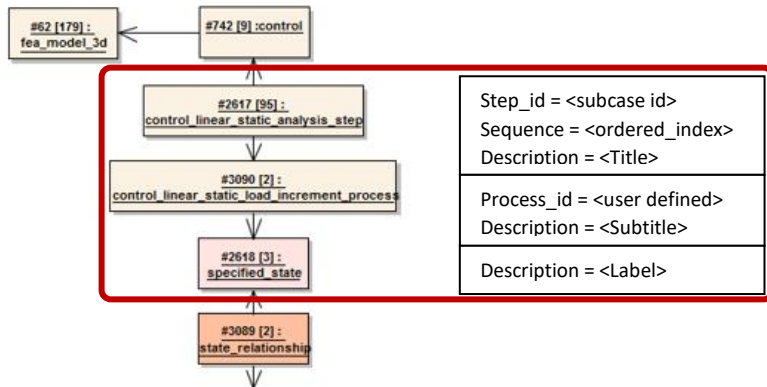


Figure 11 Aggregate View of an FEA Subcase

The pseudo listing shown in Figure 12 illustrates where these attributes might appear in a typical NASTRAN Case Control Section and notional values for each.

```

$ first subcase => <analysis_step.sequence>           1
SUBCASE <analysis_step.step_id>                       100
  TITLE=<analysis_step.description>                   'EAS Analysis 001 Model'
  SUBTITLE=<control_process.description>               'Subcase 100 -34T_Limit'
  LABEL=<specified_state.description>                   'Pull Up'

$ second subcase => <analysis_step.sequence>           2
SUBCASE <analysis_step.step_id>                       237
  TITLE=<analysis_step.description>                   'EAS Analysis 001 Model'
  SUBTITLE=<control_process.description>               'Subcase 237 +07R_Limit'
  LABEL=<specified_state.description>                   'Roll Left'

$ etc...

```

Figure 12 NASTRAN Source Data Mapping for STEP Analysis\_Step

The **control\_process.process\_id** and the top level **specified\_state.state\_id** should be populated with user defined identifiers that can include the **analysis\_step.step\_id** for readability. These guidelines are reflected in the pilot study STEP files that were used for developing this handbook. No additional guidance is provided for the state relationship instances.

## 6 Pilot Model States

The concept of steps and states was introduced in Section 5. This section greatly expands on these concepts and give examples taken from the pilot study models.

The **control\_linear\_static\_load\_increment\_process** and the single **state** entity that it refers to (**final\_input\_state**) collects all the information specified for boundary conditions and applied loads. The use of **state** entities, **state\_definition(s)** and **state\_relationship(s)** provides the flexibility needed to represent the boundary conditions, applied loads and combinations that are specified in the pilot study models. Using tree structures also enables reuse of lower level entities that are used in more than one load step. Even though the pilot study models are simplistic, the subcase, loads and boundary conditions specifications use typical constructs that can be found in a majority of linear static analysis models. Boundary conditions are discussed first followed by applied loads.

### 6.1 Specified States Related to Boundary Conditions

The ATS model boundary conditions are specified as fixed displacements at a node or nodes. These constrain the rigid body motion of the model that would normally result from application of external forces and moments if the model were in a free state. The specification of displacements is restated as specifying values for degrees of freedom (DOF) in the solution.

A full discussion of matrix algebra and partitioning as related to the Finite Element Method is beyond the scope of this handbook but a brief discussion of the foundation is presented to provide context to the discussion of displacement boundary conditions and constrained degrees of freedom. In the matrix form of the familiar Hook's Law equation  $\{F\} = -[K] * \{X\}$ , the X vector represents the displacements of the nodes of the finite element model, K represents the stiffness matrix, and F is the vector of applied forces. Static equilibrium is achieved when this equation is satisfied and all forces sum to zero at all points in all directions. A non-trivial unique solution requires a boundary condition that constrains the rigid body motion of the model. Typically, this is accomplished by specifying zero displacement at enough DOFs to prevent (at a minimum) the rigid body motion of the model and allow only elastic deformation (additional DOFs can be specified if desired). The resulting vector of displacements at the nodal DOFs are referred to as the deformed shape of the model for a particular subcase. The calculated forces at these constrained DOFs are referred to as reaction forces since they react/balance the applied loads. The number of free DOFs at each point can be reduced for other model types and solutions, but for the 3 dimensional models discussion here, assume all 6 degrees of freedom are present at each node.

#### 6.1.1 NASTRAN Specification of Constraints

A boundary condition that enforces a value for one or more of these DOFs in NASTRAN is specified on the SPC, SPC1 or SPCD bulk data card entries. The base card name is an acronym for 'single point constraint' and the name has been retained in the AP209 ed2 schema class that represents this concept. The alternate NASTRAN forms, SPC1 and SPD, enable more efficient specification of sets of constraints at multiple nodes in the solver. The SPC1 form is used in the ATS pilot models and is represented using the same AP209 ed2 constructs as a basic SPC. There are several variations of the SPC1 card used in the ATS pilot models and the NASTRAN card image and examples are shown in Figure 13. Refer to the NASTRAN Quick Reference Guide for further details.

	1	2	3	4	5	6	7	8	9	10
SPC1	SID	C	G1	G2	G3	G4	G5	G6		
	G7	G8	G9	-etc.-						

*\$ ATS2 - all degrees of freedom (dof=1-6) on node 1 are fixed, displacement = 0*  
 SPC1      100          123456    1

*\$ ATS3 - the x translation (dof=1) is fixed for nodes 1,12,34 and 45*  
 SPC1      101          1            1            12          34          45

*\$ ATS3 - the x and y rotations (dof=45) are fixed to ground for node ids in range 1 through 55*  
 SPC1      110          45          1            THRU      55

Figure 13 Single Point Constraint Specification in NASTRAN

The SID field represents the set ID of the SPC1 card and is selected in the case control using an SPC=<set\_id> entry. This set ID corresponds to the SPC Case Control Section record in Table 1 (not to be confused with the SPC Bulk Data card). Many SPC1 bulk data cards may be specified with the same or different SIDs. The 'C' field represents the degrees of freedom that are being constrained. NASTRAN input for this field is any unique combination of integers 1 through 6 with no embedded blanks or spaces representing each DOF to be constrained. There are special cases where this value can be blank or 0 but they do not apply to nodes used to define the model shape. The G(i) fields are node IDs where the DOFs specified are constrained. If non-zero enforced displacement boundary conditions were defined, an accompanying SPCD would be required to define the real value to be enforced. However, for simplicity, all the ATS pilot models use only SPC1 cards with no accompanying SPCD. This implies that specified DOFs are all constrained to zero displacement for each ATS pilot model.

Lastly, multiple sets can be added together to form a complete set of constraints referenced from the case control. Different subcases can reference individual SPC1 sets or the combined set defined on the SPCADD bulk data card. This card simply defines an additional set ID and a list of the individual set IDs to be combined.

The ATS3 pilot model, which is a shell element model, demonstrates this usage scenario by constraining the model on the end closest to the origin to prevent rigid body motion without over constraining the model. For the tension only subcase, Poisson's effect will cause a displacement in the Y-axis due to a force applied in the X-axis and therefore, the Y-axis translation should only be constrained at a single node at the fixed end while the displacement of the remaining nodes on the end are only constrained in the X-axis. The intent of how constraints are specified should be captured to the greatest extent possible.

Figure 14 shows the case control and combined SPC1 and SPCADD used for ATS3 subcase 1.

```

$ ATS3 Case control fragment for subcase 1
SUBCASE 1
  SUBTITLE=subcase1
  SPC = 11
...
$ ATS3 Corresponding bulk data entries referenced by SPC=11
SPCADD  11      100      101      110

SPC1    100      123      23
SPC1    101      1        1        12      34      45
SPC1    110      45      1        THRU    55
SPC1    110      45      57      58      59      60      61      62
        64      65      66      67      68      69      71      72
        73      74      75      76      78      79      80      81
        82      83      85      86      87      88      89      90

```

*Figure 14 Boundary Conditions for ATS3 Subcase 1*

A brief explanation of each entry follows. The set ID 100 specifies that node 23 is constrained in the xyz translational directions. Set ID 101 constraints the x translation for nodes 1, 12, 34 and 45. All these nodes are on the fixed edge of the shell model nearest the origin. The set ID 110 entries constrain the x and y rotational degrees of freedom at all the nodes specified. Finally, SPCADD 11 combines all of these constraints into one set that is referenced on the case control entry. Note that the z rotational DOF is not constrained anywhere. This was intentional because the NASTRAN shell element does not normally have any stiffness in rotational DOF about the element normal axis. These additional degrees of freedom are constrained by other mechanisms during the solution process and are currently not included in the STEP representation.

The boundary conditions for the other ATS models and subcases follow similar concepts but are tailored to the element types and applied loads. Lastly, each constrained DOF in a model will have a reaction force associated with the constrained DOF at the end of the solution process.

### 6.1.2 AP209 ed2 Specification of Constraints

The STEP equivalent of the NASTRAN single point constraint is the **single\_point\_constraint\_element**. This entity is a sub-class of the general **constrain\_element** class. The **single\_point\_constraint\_element** is defined as a constraint on a node, group of nodes or a geometry element. The constraint element definitions are taken from the AP209 ed2 Recommended Practices document shown in Figure 15. The highlighted case represents a **single\_point\_constraint\_element** applied to a node as is used in the ATS pilot models.

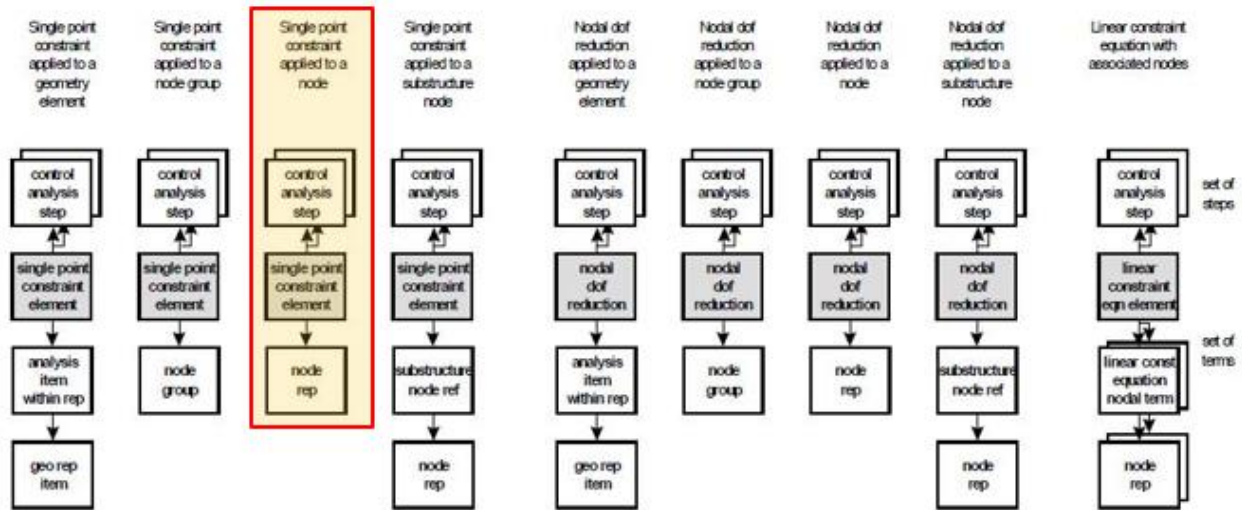


Figure 15 Constraint Definition Reference

A common question arises concerning why the node constraints in NASTRAN are mapped to a **constraint\_element** class subtype in STEP? The reason is that the treatment of constraints in STEP has been split into two separate concepts that are consistent with how these constraints are cast in the finite element solution. A constraint equation is applied to a degree of freedom and is generally expressed as  $A(i) \times \text{DOF}(i) = B(i)$ , where 'A' is a coefficient and 'DOF' is the specified degree of freedom at a node and 'B' is the specified value for every instance 'i'. The left side of this equation is captured by the **freedoms\_and\_values** attribute (a set of **freedom\_and\_coefficient(s)**) and a **required\_node** attribute (node\_output\_reference type) for each **single\_point\_constraint\_element** entity. The **single\_point\_constraint\_element** also contains a set of **control\_analysis\_steps** references to indicate which subcases this constraint element applies to. The right side of the equation is captured by the **single\_point\_constraint\_element\_values** entity that references the **single\_point\_constraint\_element**. This entity contains a **degrees\_of\_freedom** attribute and an attribute 'b' which is a list of values corresponding to B(i). Part 104, Section 6.4.11 presents similar information.

The key takeaway from this discussion is that the **single\_point\_constraint\_element** is related directly to the **control\_linear\_static\_analysis\_step(s)** while the **single\_point\_constraint\_element\_values** are part of the final input state definition. This allows the same constraint element to be specified once, but have enforced constraint values that are different for each subcase. While this capability is not exercised directly in the pilot study models (all constraints are zero valued), this scenario is supported in many commercial FEA solvers and the AP209 ed2 data model supports it.

The EXPRESS schema for these entities is shown in Figure 16.

```

ENTITY single_point_constraint_element;
  ENTITY constraint_element;
    element_id                : IDENTIFIER;
    steps                      : SET [1:?] OF control_analysis_step;
  ENTITY single_point_constraint_element;
    required_node           : NODE_OUTPUT_REFERENCE;
    coordinate_system         : fea_axis2_placement_3d;
    freedoms_and_values     : SET [1:?] OF freedom_and_coefficient;
    description               : TEXT;
END_ENTITY;

ENTITY freedom_and_coefficient;
  freedom                  : DEGREE_OF_FREEDOM;
  a                        : MEASURE_OR_UNSPECIFIED_VALUE;
END_ENTITY;

ENTITY single_point_constraint_element_values;
  ENTITY state_definition;
    defined_state             : state;
  ENTITY single_point_constraint_element_values;
    element                   : single_point_constraint_element;
    degrees_of_freedom     : freedoms_list;
    b                       : LIST [1:?] OF MEASURE_OR_UNSPECIFIED_VALUE;
END_ENTITY;

TYPE DEGREE_OF_FREEDOM = SELECT
  (ENUMERATED_DEGREE_OF_FREEDOM,
   APPLICATION_DEFINED_DEGREE_OF_FREEDOM);
END_TYPE;

TYPE MEASURE_OR_UNSPECIFIED_VALUE = SELECT
  (CONTEXT_DEPENDENT_MEASURE,
   UNSPECIFIED_VALUE);
END_TYPE;

TYPE NODE_OUTPUT_REFERENCE = SELECT
  (node_representation,
   node_group,
   substructure_node_reference,
   analysis_item_within_representation);
END_TYPE;

```

Figure 16 EXPRESS Schema Related to Single\_Point\_Constraint\_Element

### 6.1.3 AP209 ed2 Instantiation of Constraints

The preceding discussion focused on the EXPRESS classes and relationships that are used to specify the AP209 ed2 data model for analysis controls, and for boundary conditions in particular. No direction is explicitly given on how to structure the state definitions to represent common usage patterns provided by FEA solvers such as NASTRAN. This section discusses one such mapping but is not necessarily the only possible mapping. Other solvers may require different mapping.

All the boundary condition constructs specified in the ATS pilot models can be built using a 3 layered state definition hierarchy. Figure 17 shows an example diagram of this 3 layer organization. The red text

labels indicate the NASTRAN card concept that the **specified\_state** instance on each layer represents. State relationships are indicated as ovals with the letter 'R'. This diagram illustrates two subcases (step ID 1 and 2) that reference two unique constraint set IDs (3 and 4) that have unique enforced values for a single constraint element, at a single node, used in both subcases.

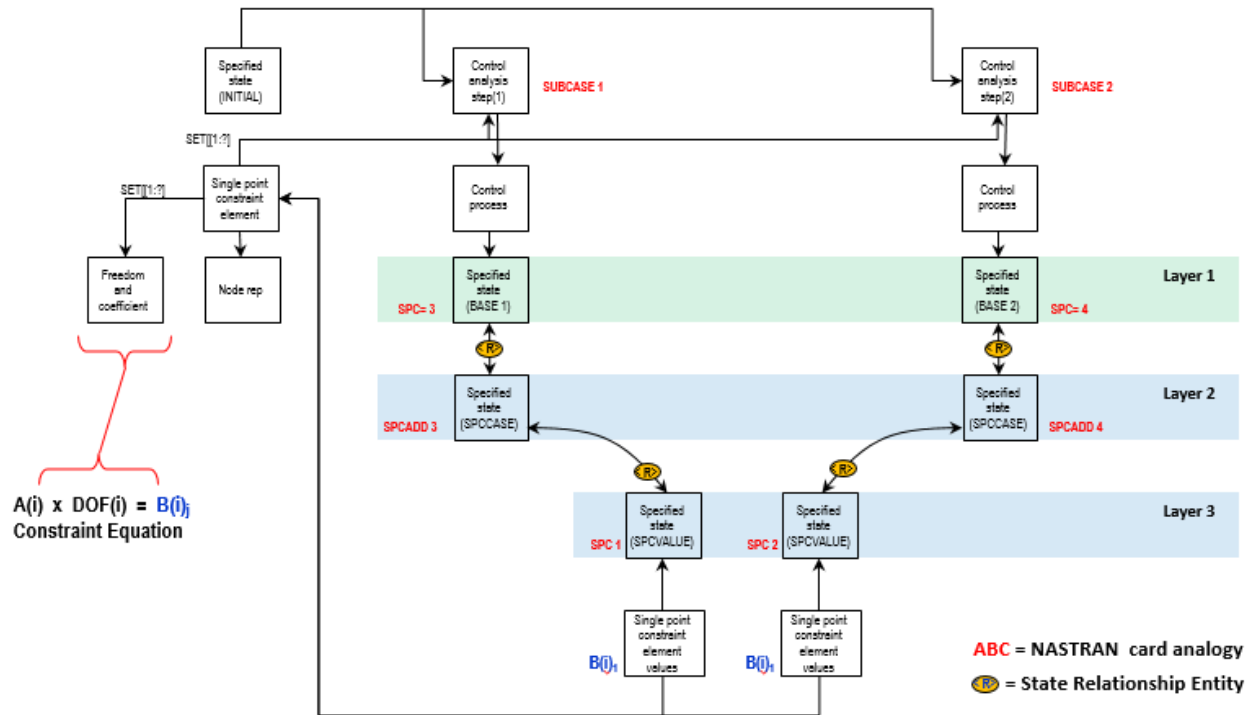


Figure 17 Example of 3 Layer Organization for Constraint Boundary Conditions

Layer 1 maps to the constraint set selected in the case control. The Layer 2 maps to the constraint combinations specified on 2 different SPCADD cards. These specified states are considered to be 'aggregation' states. In cases where there are no multiple constraints being aggregated (as shown), the layer 2 **specified\_state** is optional. However, even in the absence of the SPCADD card, a layer 2 **specified\_state** can be instantiated as a pass-thru entity for consistency. Lastly, layer 3 maps to the actual constraint set bulk data cards. These are considered to be 'value' states that are referenced from the **single\_point\_constraint\_element\_values** instances that specify the enforced value for this subcase and for the specified degrees of freedom. The 'value' **specified\_state** of these **state\_definition(s)** should match the constraint set identifier used in the bulk data.

In all cases, the selected constraint set ID must match the ID of the first constraint **specified\_state** in layer 2 or layer 3.

Figure 18 is a variation of Figure 17 where two constraint elements at two nodes are related to both subcases. The case control for each subcase selects the same constraint set, which is an SPCADD card combining the same two constraint sets on layer 3. The **single\_point\_constraint\_element\_values** instances specify a value for each constraint equation at each node. Note that the layer 2 **specified\_state** instances could be collapsed into a single instance and two of the relationship instances eliminated. While optimization and minimization of entities is a goal, there can be valid reasons not tied to the standard to use explicit instances where one would suffice. One such reason could be situations where a unique attribute value is set based on the usage by a higher level entity. For example, each layer 2 **specified\_state** could contain the subcase ID as a part of its description attribute from the referencing **analysis\_step**. This can aid readability of the STEP file but is not to be relied on by any pre or post processor.

This organization provides great flexibility but also puts more requirements on the recommended practices documentation to ensure interoperability of the resulting data models.

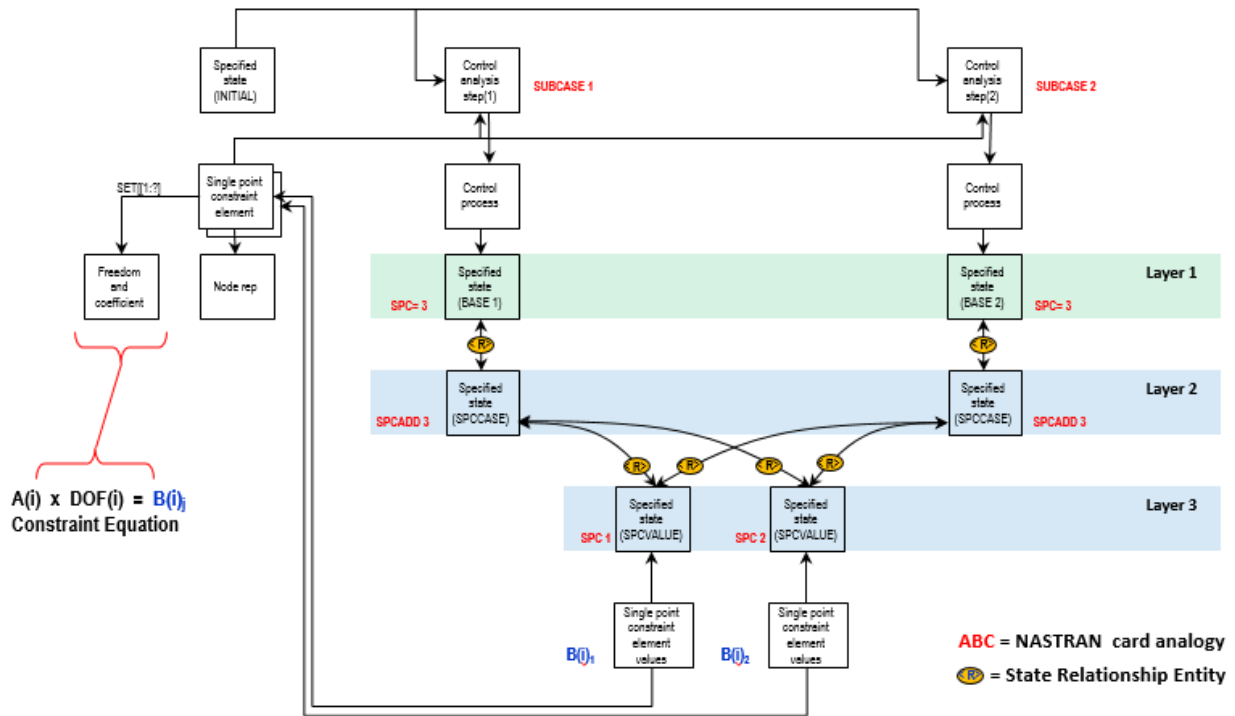


Figure 18 Variation of 3 Layer Organization of Constraint Boundary Conditions



A fragment of the AT51 pilot study model input is shown in Figure 19. This corresponds to one load case with one **single\_point\_constraint\_element** and one **single\_point\_constraint\_element\_values** entities. This matches a single column of the diagram in Figure 16. Only the translational degrees of freedom are constrained at node 1 in this case.

```

$ AT51 Case control fragment for subcase 1
SUBCASE 1
  SUBTITLE=subcase1
  SPC = 100
  ...

$ AT51 Corresponding bulk data entries referenced by SPC=100
SPC1    100    123    1
  
```

Figure 19 NASTRAN AT51 Boundary Conditions

Figure 20 is the AT51 pilot study model diagram for instantiation of these boundary conditions. This diagram uses the same notation as Volume 1 of this handbook. Not all related instances are shown.

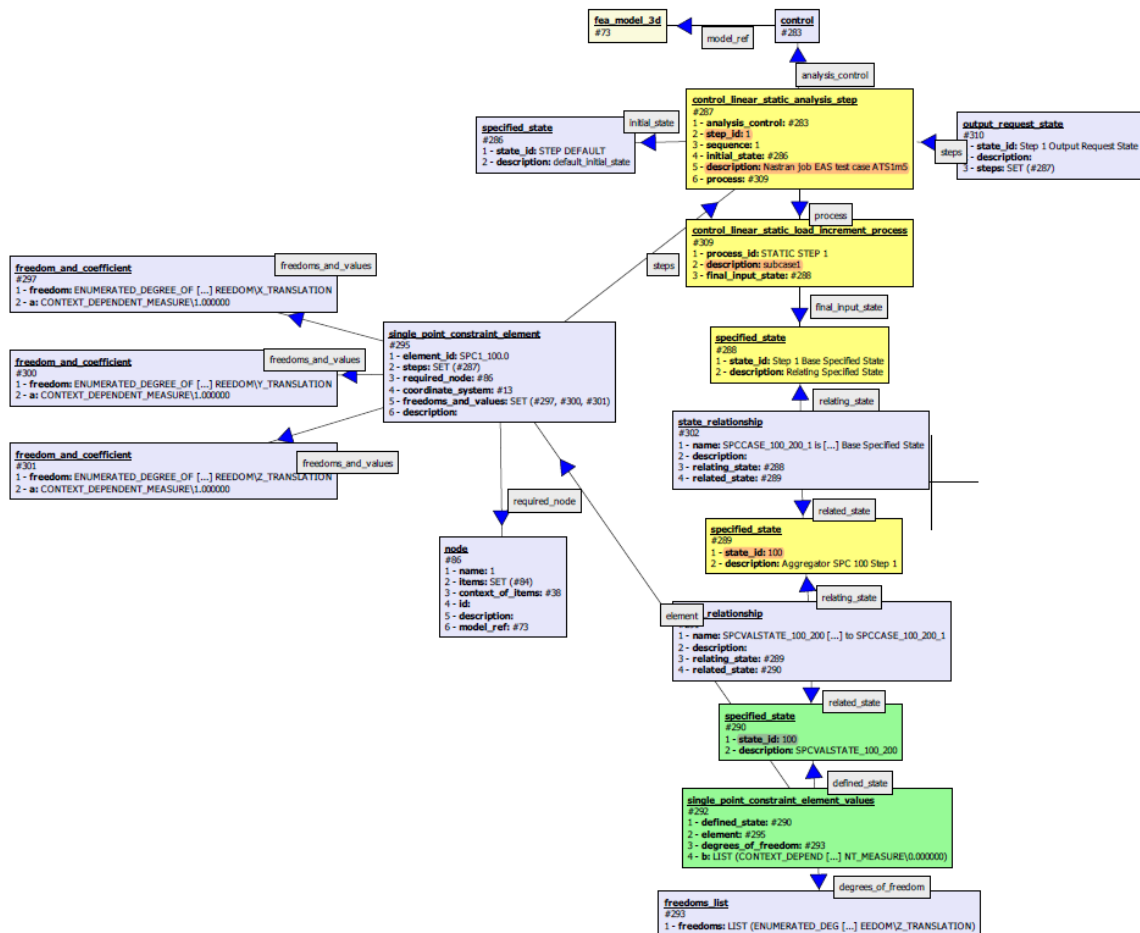


Figure 20 AT51 Boundary Condition Instance Diagram

The corresponding STEP file fragment for these entities is shown in Figure 21. The order of the entities follows the diagram from top to bottom and some reformatting has been done for readability. Note the **context\_dependent\_measure** values equal to 0 and the coefficients for the DOFs equal to 1.

```
#73= FEA_MODEL_3D('Identification',(#13),#28,
  'NASTRAN BDF Converter v0.0.0',('NASTRAN'),'AnalysisModelType');

#283= CONTROL(#73,'Control.0','FemConvert','Nastran job EAS test case ATSlm5',
  ('101','TIME 600','CEND','0','1','ENDDATA'),('NASTRAN'));

#287= CONTROL_LINEAR_STATIC_ANALYSIS_STEP(#283,'1',1,#286,
  'Nastran job EAS test case ATSlm5',#309);
#286= SPECIFIED_STATE('STEP DEFAULT','default_initial_state');
#309= CONTROL_LINEAR_STATIC_LOAD_INCREMENT_PROCESS('STATIC STEP 1','subcase1',#288);

#288= SPECIFIED_STATE('Step 1 Base Specified State','1');
#302= STATE_RELATIONSHIP(
  'SPCCASE_100_200_1 is related to Step 1 Base Specified State','',#288,#289);

#289= SPECIFIED_STATE('100','Aggregator SPC 100 Step 1');
#291= STATE_RELATIONSHIP(
  'SPCVALSTATE_100_200 is related to SPCCASE_100_200_1','',#289,#290);

#290= SPECIFIED_STATE('100','SPCVALSTATE_100_200');
#292= SINGLE_POINT_CONSTRAINT_ELEMENT_VALUES(#290,#295,#293,(
  CONTEXT_DEPENDENT_MEASURE(0.),
  CONTEXT_DEPENDENT_MEASURE(0.),
  CONTEXT_DEPENDENT_MEASURE(0.)));
#293= FREEDOMS_LIST((
  ENUMERATED_DEGREE_OF_FREEDOM(.X_TRANSLATION.),
  ENUMERATED_DEGREE_OF_FREEDOM(.Y_TRANSLATION.),
  ENUMERATED_DEGREE_OF_FREEDOM(.Z_TRANSLATION.)));

#295= SINGLE_POINT_CONSTRAINT_ELEMENT('SPC1_100.0',(#287),#86,#13,(#297,#300,#301),'');
#297= FREEDOM_AND_COEFFICIENT(
  ENUMERATED_DEGREE_OF_FREEDOM(.X_TRANSLATION.),CONTEXT_DEPENDENT_MEASURE(1.));
#300= FREEDOM_AND_COEFFICIENT(
  ENUMERATED_DEGREE_OF_FREEDOM(.Y_TRANSLATION.),CONTEXT_DEPENDENT_MEASURE(1.));
#301= FREEDOM_AND_COEFFICIENT(
  ENUMERATED_DEGREE_OF_FREEDOM(.Z_TRANSLATION.),CONTEXT_DEPENDENT_MEASURE(1.));

#86= NODE('1',(#84),#38,#73);
```

Figure 21 STEP Part 21 File Fragment of ATS1 Boundary Conditions

Similar figures can be constructed for all the ATS pilot study models. However, for surface and volume element models with several load cases and combinations of boundary conditions, these diagrams become very large and complex and are not included here.

## 6.2 Specified States Related to Applied Loads

The applied loads are treated in a similar manner to constraints with the exception that the associated **state\_definition(s)** reference existing model entities such as nodes or element aspects (face, edge, corner, etc..). The tree structure of **states**, **state\_relationship(s)** and **state\_definition(s)** is defined to capture the specification of loads for each subcase.

### 6.2.1 NASTRAN Specification of Applied Loads

The loads used in the pilot study model are NASTRAN nodal forces, moments, and pressures. There are many other loading types in NASTRAN but the loads used in the pilot study are typical and demonstrate how these entities are mapped to AP209 ed2 entities. The FORCE and PLOAD2 cards are used for application of point loads on nodes and pressure loads on the faces of surface elements. Figure 22 shows the card format used for these two bulk data entries and several examples for the ATS pilot models.

1	2	3	4	5	6	7	8	9	10
FORCE	SID	G	CID	F	N1	N2	N3		
1	2	3	4	5	6	7	8	9	10
PLOAD2	SID	P	EID1	EID2	EID3	EID4	EID5	EID6	

```

$ ATS1 - 1000 lb force applied to node 17 in -X direction of the basic coordinate system
FORCE 200 17 0 1000. -1. 0. 0.

$ ATS3 - pressure lb/sq inch applied to the face of elements 8 and 9 normal to the element
PLOAD2 500 -125.0 8
PLOAD2 500 -125.0 9

```

Figure 22 Applied Loads Specification in NASTRAN

Both inputs have a SID field that represents the applied load set ID. This set ID corresponds to the LOAD Case Control Section record in Table 1 (not to be confused with the LOAD Bulk Data card). Many load cards can be specified that share the same SID or specified with independent SID(s). The FORCE card field 'G' defines the node ID that the force is applied. The 'CID' is the ID of the coordinate system that the direction vector information ('N1', 'N2', and 'N3') should be interpreted in. Lastly, the field 'F' defines the magnitude of the total force applied at the node in the vector direction specified. The pure vector definition of the applied force is simply  $F*N1$ ,  $F*N2$ ,  $F*N3$  in coordinate system 'CID'. The example listed above is an applied force of 1000.0 lb in the  $-X$  direction of the basic coordinate system (CID=0 or blank).

The PLOAD2 card defines a pressure applied normal to the plane of the element. A positive value of 'P' results in a net force that acts in the same direction as the positive normal to the element plane, in other words, the +Z axis of the local element coordinate system. This pressure is multiplied by the area of the element to compute the total load applied to the element. Multiple element ID(s) can be specified on each card to apply the pressure to larger regions of the model or multiple PLOAD2 cards with the same SID can be specified.

Load specifications can be combined into a single composite set ID that is referenced by the case control LOAD=SID entry. This is accomplished using the LOAD Bulk Data card and is illustrated in Figure 23.

1	2	3	4	5	6	7	8	9	10
LOAD	SID	S	S1	L1	S2	L2	S3	L3	
	S4	L4	-etc.-						

*\$ AT3 - combination of load sets 200, 300 and 400 with unit scale factors*

LOAD	23	1.	1.	200	1.	300	1.	400	
------	----	----	----	-----	----	-----	----	-----	--

*\$ AT3 - all core load definitions for axial and lateral load combination*

FORCE	200	62	0	125.	-1.	0.	0.		
FORCE	200	69	0	250.	-1.	0.	0.		
FORCE	200	76	0	250.	-1.	0.	0.		
FORCE	200	83	0	250.	-1.	0.	0.		
FORCE	200	90	0	125.	-1.	0.	0.		
FORCE	300	55	0	10.	0.	-1.	0.		
FORCE	300	90	0	10.	0.	-1.	0.		
FORCE	400	85	0	20.	0.	-1.	0.		
FORCE	400	86	0	20.	0.	-1.	0.		
FORCE	400	87	0	20.	0.	-1.	0.		
FORCE	400	88	0	20.	0.	-1.	0.		
FORCE	400	89	0	20.	0.	-1.	0.		

Figure 23 Linear Load Combination Used in Subcase 3 of AT3

In addition to combining loads, this card provides scale factors for each individual load set and an overall scale factor for the linearly superimposed load sets. The field 'S(i)' is the individual scale factors applied to the individual 'L(i)' sets being linearly superimposed. The field 'S' is the overall scale factor. Older versions of MSC/NASTRAN did not allow combined LOAD cards to reference other combined LOAD cards; however, this restriction was removed in later releases. Therefore, a LOAD card can now form a deep nested structure. The pilot study models do not use any deep nested load combinations; however, the 3 layer organization is still valid as the second layer would handle all combinations of loads.

There are many other load specification cards defined for the various versions of NASTRAN. The loads discussed herein cover the pilot study models used for development of this handbook. As such, implementations should clearly state which cards and which options are supported.

### 6.2.2 AP209 ed2 Specification of Applied Loads

The AP209 ed2 standard defines specialized entities to represent the many different ways that loads can be applied to an FE model. The recommended practices document summarized these in Section 2.11.3.3 States and State Definitions. The figures from the recommended practices document are repeated here in Figure 24 and Figure 27, with highlights indicating the **state\_definition(s)** used in the pilot study models. The details of each of these specialized **state\_definition(s)** can be investigated in the Part 104 document or by reviewing the EXPRESS schema.

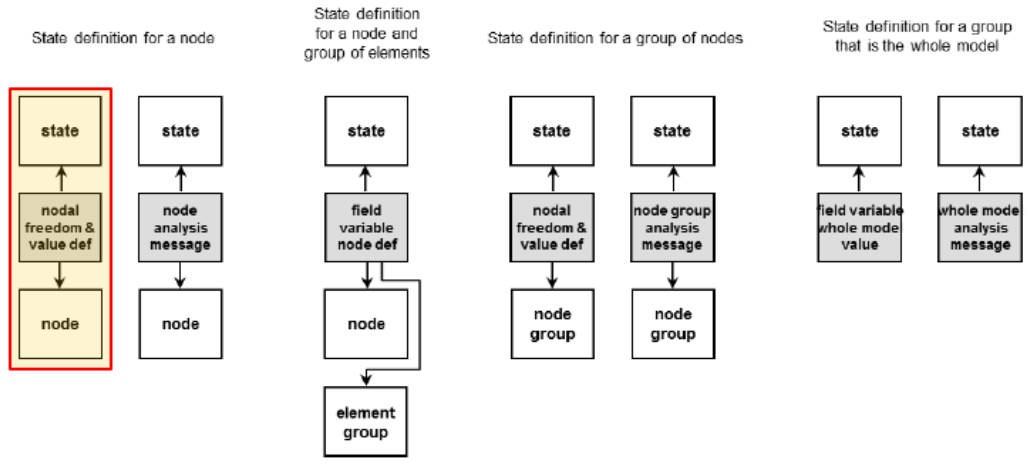


Figure 24 Recommended Practices Figure for State\_Definitions Related to Nodes (Nodal Force)

The **nodal\_freedom\_and\_value\_definition** shown in Figure 24 is further specialized to **nodal\_freedom\_action\_definition**. The inheritance diagram is shown in Figure 25 and the flattened EXPRESS listing is shown in Figure 26. Following the inheritance is straight forward as the base class provides the link to the state entity, the **nodal\_freedom\_and\_value\_definition** adds the attributes for node references, coordinate systems, degrees of freedom and the list of values. Lastly, the **nodal\_freedom\_action\_definition** adds the action attribute which is an enumerated list defining how to interpret these data values.

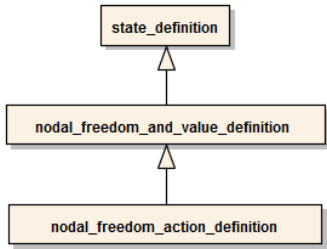


Figure 25 Inheritance Diagram for Applied Loads at Nodes Mapped from NASTRAN FORCE Card

```

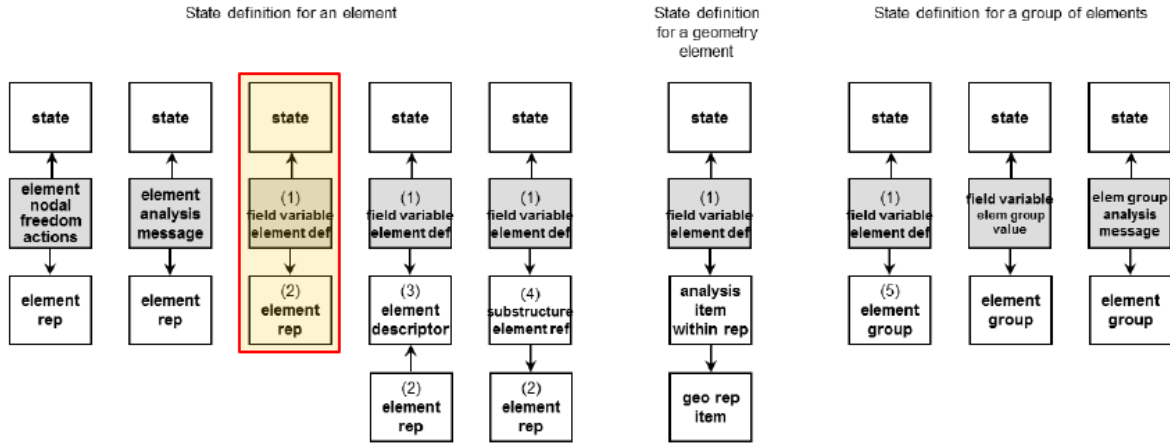
ENTITY nodal_freedom_action_definition;
  ENTITY state_definition;
    defined_state : state;
  ENTITY nodal_freedom_and_value_definition;
    node : NODE_OUTPUT_REFERENCE;
    coordinate_system : fea_axis2_placement_3d;
    degrees_of_freedom : freedoms_list;
    values : LIST [1:?] OF MEASURE_OR_UNSPECIFIED_VALUE;
  ENTITY nodal_freedom_action_definition;
    action : ACTION_TYPE;
END_ENTITY;

TYPE ACTION_TYPE = ENUMERATION OF
  (APPLIED_LOADS,
  RESIDUAL_LOADS);
END_TYPE;

```

*Figure 26 Flattened EXPRESS Schema for Nodal Loads*

The state definitions for an element shown in Figure 27 should be interpreted as defined by the integer tags enclosed in parentheses. The highlighted state definition has a (1) tag on the **field\_variable\_element\_definition** and a (2) tag on the **element\_representation**. Using the table below the figure completes the proper state definition. Therefore, an element pressure load is represented as a **surface\_3d\_element\_field\_value\_definition** and references a **surface\_3d\_element\_representation**. This is consistent with the ATS3 pilot study model pressure loads. However, this is still not the final class instantiated.



(1)	(2)	(3)	(4)	(5)
volume_3d_element_field_value_defn	volume_3d_element_rep	volume_3d_element_descriptor	volume_3d_substructure_element_ref	volume_3d_element_grp
volume_2d_element_field_value_defn	planar_volume_2d_element_rep	planar_volume_2d_element_descriptor	volume_2d_substructure_element_ref	volume_2d_element_grp
volume_2d_element_field_value_defn	axisymmetric_volume_2d_element_rep	volume_2d_element_descriptor	volume_2d_substructure_element_ref	volume_2d_element_grp
surface_3d_element_field_value_defn	surface_3d_element_rep	surface_3d_element_descriptor	surface_3d_substructure_element_ref	surface_3d_element_grp
surface_2d_element_field_value_defn	planar_surface_2d_element_rep	planar_surface_2d_element_descriptor	surface_2d_substructure_element_ref	surface_2d_element_grp
surface_2d_element_field_value_defn	axisymmetric_surface_2d_element_rep	axisymmetric_surface_2d_element_desc	surface_2d_substructure_element_ref	surface_2d_element_grp
curve_3d_element_field_value_defn	curve_3d_element_rep	curve_3d_element_descriptor	curve_3d_substructure_element_ref	curve_3d_element_grp
curve_2d_element_field_value_defn	planar_curve_2d_element_rep	planar_curve_2d_element_descriptor	curve_2d_substructure_element_ref	curve_2d_element_grp
curve_2d_element_field_value_defn	axisymmetric_curve_2d_element_rep	axisymmetric_curve_2d_element_desc	curve_2d_substructure_element_ref	curve_2d_element_grp

Figure 27 Recommended Practices Figure for State\_Definitions Related to Elements (Face Pressure)

The **field\_variable\_element\_definition** shown in Figure 27 is further specialized to represent a constant applied pressure on a face of a 3d element. The instantiated class is a **surface\_3d\_element\_boundary\_constant\_specified\_surface\_variable\_value**.

The inheritance diagram is shown in Figure 28. This hierarchy diagram shows only the construction of the final class instantiated. The full class hierarchy below the **field\_variable\_definition** is quite large and complex as it also includes all the result classes. The Recommended Practices document does not provide guidance other than the figures already discussed. The Part 104 document should be used to explore what all the various classes are intended to represent. The **surface\_3d\_element\_boundary\_constant\_specified\_surface\_variable\_value** class is documented in Part 104, Section 6.7.43.

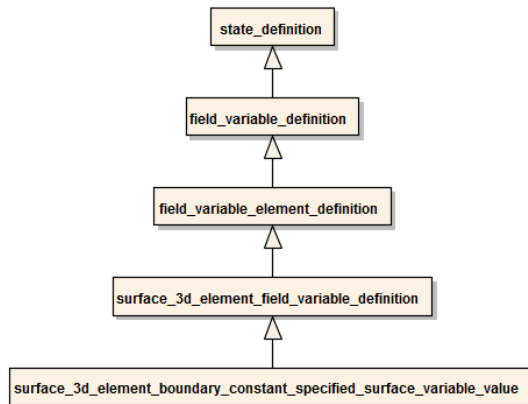


Figure 28 Inheritance Diagram for Applied Loads at Elements Mapped from NASTRAN PLOAD2 Card

The flattened EXPRESS listing is shown in Figure 29. This shows what each inheritance level adds to the final class definition. Using the flattened listing simplifies the presentation of a final class definition and is easier to understand. Determining which final class is appropriate for a NASTRAN entity is a difficult task when implementing a NASTRAN to AP209 ed2 converter. The LOTAR Engineering Analysis Work Group (EAS WG) can assist with these tasks (see References and Links for contact information).

```

ENTITY surface_3d_element_boundary_constant_specified_surface_variable_value;
  ENTITY state_definition;
    defined_state : state;
  ENTITY field_variable_definition;
  ENTITY field_variable_element_definition;
  ENTITY surface_3d_element_field_variable_definition;
    element : SURFACE_3D_ELEMENT_OUTPUT_REFERENCE;
  ENTITY surface_3d_element_boundary_constant_specified_surface_variable_value;
    simple_value : FIELD_VALUE;
    variable : BOUNDARY_VARIABLE;
    element_face : SURFACE_3D_FACE;
    coordinate_system : OPTIONAL SURFACE_3D_ELEMENT_COORDINATE_SYSTEM;
END_ENTITY;

TYPE SURFACE_3D_ELEMENT_OUTPUT_REFERENCE = SELECT
  (surface_3d_element_representation,
  surface_3d_element_descriptor,
  surface_3d_element_group,
  surface_3d_substructure_element_reference,
  analysis_item_within_representation);
END_TYPE;

TYPE BOUNDARY_VARIABLE = SELECT
  (BOUNDARY_SURFACE_SCALAR_VARIABLE,
  BOUNDARY_SURFACE_VECTOR_3D_VARIABLE,
  APPLICATION_DEFINED_SCALAR_VARIABLE,
  APPLICATION_DEFINED_VECTOR_3D_VARIABLE);
END_TYPE;

TYPE BOUNDARY_SURFACE_SCALAR_VARIABLE = ENUMERATION OF
  (PRESSURE);
END_TYPE;

TYPE SURFACE_3D_FACE = INTEGER; END TYPE;

```

*Figure 29 Flattened EXPRESS Schema for Element Pressure*

The variable is selected to be a **boundary\_surface\_scalar\_variable** which has a single enumeration equal to **.PRESSURE**. . In AP209 ed2, a positive pressure acts normal to the surface and into the volume of the element. This definition is consistent with NASTRAN volume elements, but differs from the NASTRAN surface element definition which uses the element normal to determine the positive direction as illustrated in Figure 30.



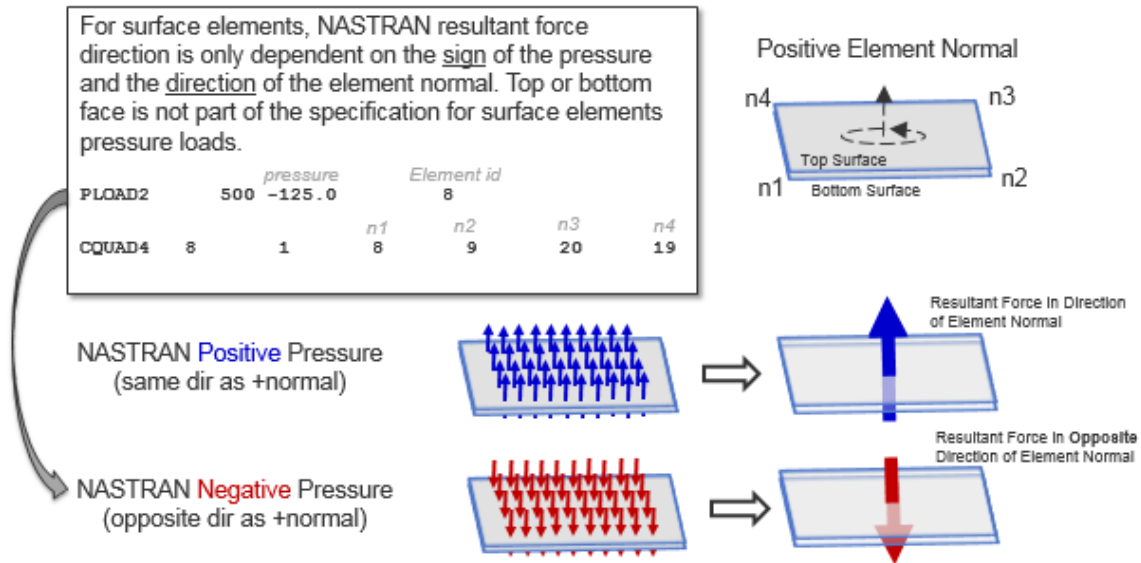


Figure 30 NASTRAN Surface Element Pressure Sign Convention

AP209 ed2 uses an **element\_face** attribute for surface elements which enables the definition of positive pressure to be consistent for both surface and volume elements. It also allows a model to capture the true physics of a problem where you may have positive pressure on both sides of a surface element that could result in a net force of zero. Figure 31 illustrates the AP209 ed2 convention.

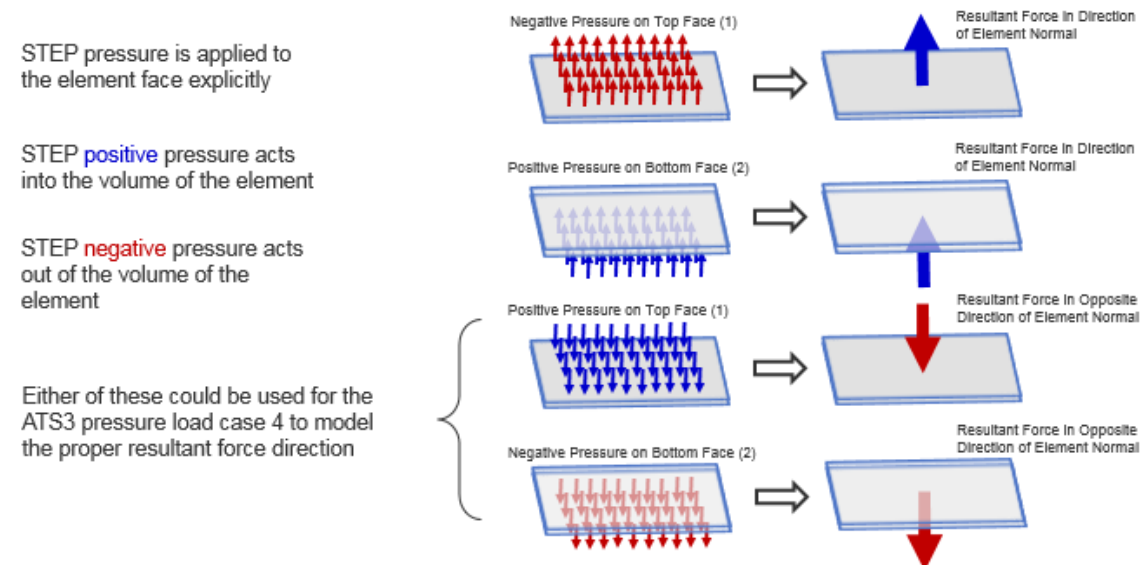


Figure 31 AP209 ed2 Convention for Positive Pressure

### 6.2.3 AP209 ed2 Superposition of Applied Loads

The next topic to be addressed is the linear superposition of the defined states for forces and pressure loads. The use of scale factors on individual load sets and the overall combination is easily mapped to AP209 ed2 constructs. The **linearly\_superimposed\_state** entity class provides this capability.

A **linearly\_superimposed\_state** is referenced from all the individual **state\_component(s)** that are being superimposed. The 'INVERSE' qualifier indicates that the value of the components attribute is determined by the set of **state\_component(s)** that reference this state. There is no explicit component attribute populated with this set of **state\_component(s)** in the ASCII Part 21 file.

The **state\_component** provides a real value **factor** attribute for scaling the **state\_definition(s)** that are related through **state\_relationship** instances. To fully define the NASTRAN load combination card, two **linearly\_superimposed\_state(s)** would be required. One collecting the scaled individual loads and another for the overall scaled load set. Figure 32 shows the flattened EXPRESS definitions.

```

ENTITY linearly_superimposed_state;
  ENTITY state;
    state_id          : IDENTIFIER;
    description       : TEXT;
  ENTITY linearly_superimposed_state;
    INVERSE
    components        : SET [1:?] OF state_component FOR state;
END_ENTITY

ENTITY state_component;
  ENTITY state;
    state_id          : IDENTIFIER;
    description       : TEXT;
  ENTITY state_component;
    state             : linearly_superimposed_state;
    factor            : CONTEXT_DEPENDENT_MEASURE;
END_ENTITY;

```

*Figure 32 Flattened EXPRESS Schema for Linearly Superimposed Load Cases with Scale Factors*

Similar to the boundary condition discussion in Section 6.1.3, all load combinations modeled with superimposed state definitions and associated scaling factors would appear in layer 2 of the 3 layer state tree. If only unit scale factors are needed, then loads could be aggregated using simple **state\_relationship** instances instead of **linearly\_superimposed\_state(s)**. However, it is recommended to be explicit when combining load state definition entries by using the **linearly\_superimposed\_state(s)** and unit scale factors. This provides an unambiguous definition that minimizes assumptions.

Several examples and diagrams are provided in the following section to illustrate the concept of load superposition and how it is expressed in AP209 ed2.

## 6.2.4 AP209 ed2 Instantiation of Applied Loads

The instantiation of applied loads in AP209 ed2 using the constructs presented in the prior section uses a similar presentation as for constraints. First, general figures are presented followed by examples from the ATS pilot models illustrating the concept.

All the applied loads in the ATS pilot study models can be instantiated using the same 3 layer approach discussed for constraints. Figure 33 is an example where a single load is reused for 2 subcases.

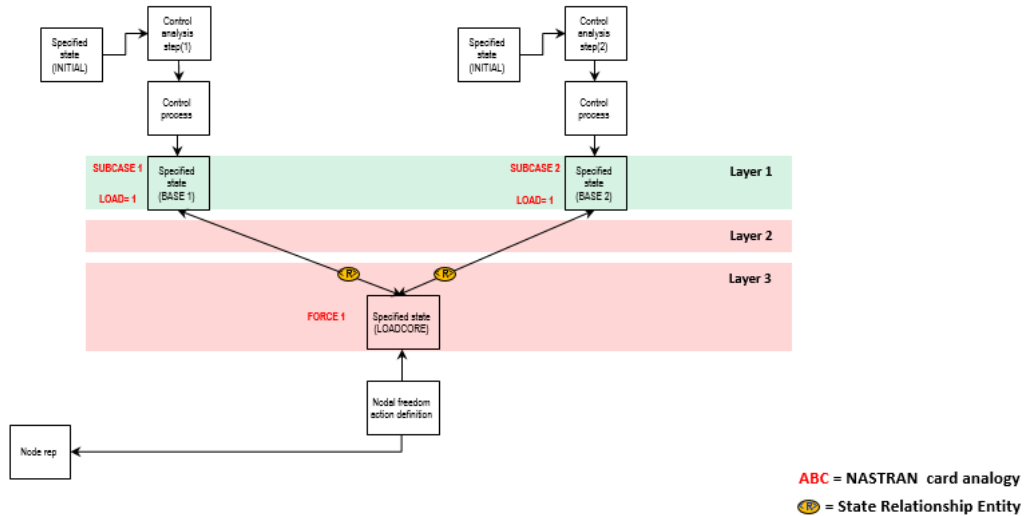


Figure 33 Example of Shared Single Applied Load

The 'base' **specified\_state**(s) in layer 1 are shared with the constraint definitions since only one reference from the control process is allowed. It represents the load set selected in the case control. Since no combinations are used, there are no layer 2 entities. The **state\_relation** directly relates the **state\_definition** for applied forces at nodes to the 'base' **specified\_state**. For discussion, these **state\_definition**(s) refer to the 'loadcore' **specified\_state** in layer 3.

Figure 34 illustrates a more complex example. There are three subcases, the first two subcases share the same **linearly\_superimposed\_state** which is a scaled combination of three 'loadcore' **state\_definition**(s).

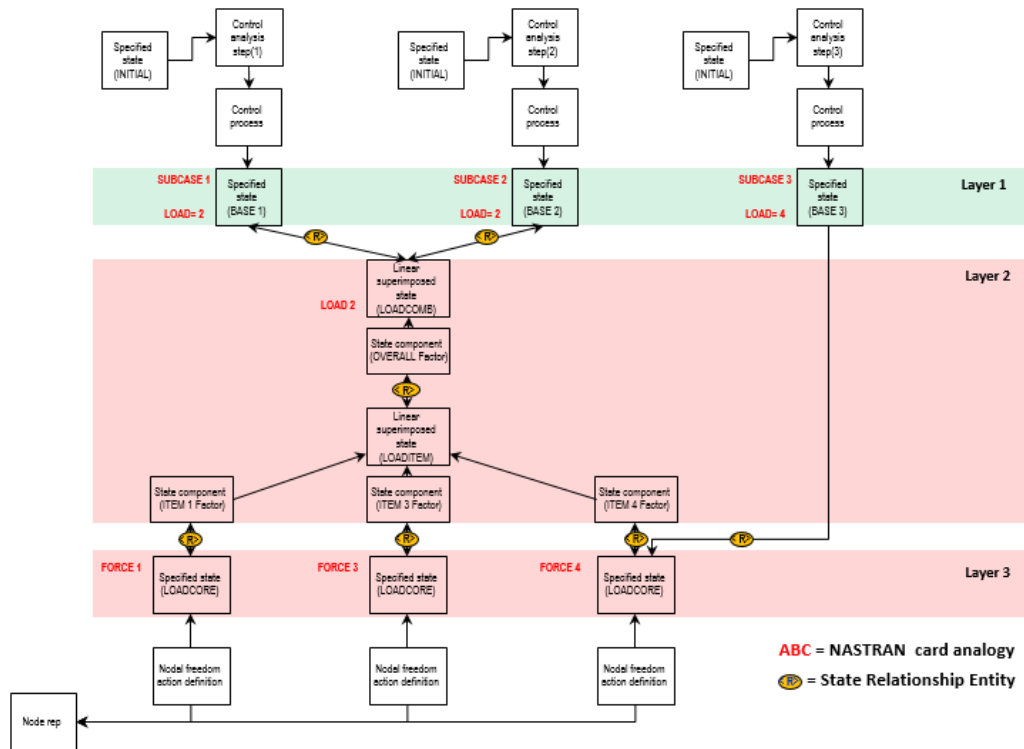


Figure 34 Example of Combined Applied Loads

Subcase 3 is a direct selection of one of the un-scaled state\_components. The additional terminology such as 'base', 'loadcore' and the others found in these figures such as 'loadcomb' and 'loaditem' are simply textual aids for discussion. They were used in the labeling of these instances in the ASCII Part 21 files to help with debugging but are currently not specified in the standard or the recommended practices.

The recommended practice defines where material, node and element IDs should be located in the data model; however, currently no guidance is provided for the boundary condition or load set IDs. To reproduce a solver input listing from the STEP population, a convention for load and boundary condition set IDs must be adopted by the implementors.

A convention for subcase and constraint set identification has been described in sections 5.3 and 6.1.3. A similar convention should be used for load set identifications. In the hierarchy of **specified\_state(s)**, the top-most **specified\_state** related to the 'base' state should use the **state\_id** that matches the selected load set ID for that step. Similarly, the lowest **specified\_state** in the hierarchy (layer 3) should use the load set identification found on the source load definitions (FORCE or PLOAD2 entries in the NASTRAN source). Note that a **specified\_state** can assume both roles if the selected set is the load definition set as illustrated in subcase 3 from Figure 34 or subcase 4 of Figure 36.

Finally, load cases for ATS3 are presented in Figure 35 and Figure 36. These figures show only a relevant subset of the entities used to model the applied loads for the ATS3 pilot study model in AP209 ed2.

The guidelines provided in this handbook present a working solution for loads and boundary conditions as defined for the pilot test models. Guidelines for other solvers and other NASTRAN case control will be addressed as additional test cases are introduced and the translator implementations mature.

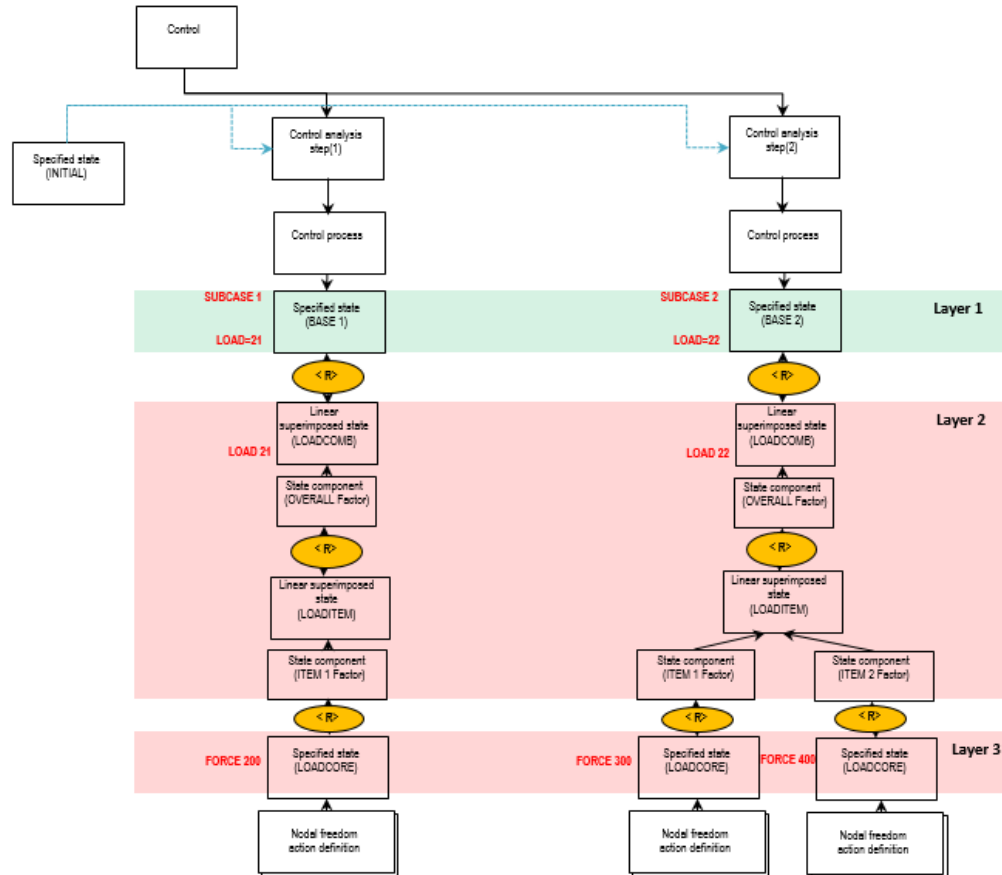


Figure 35 ATS3 Applied Loads Subcase 1 and 2

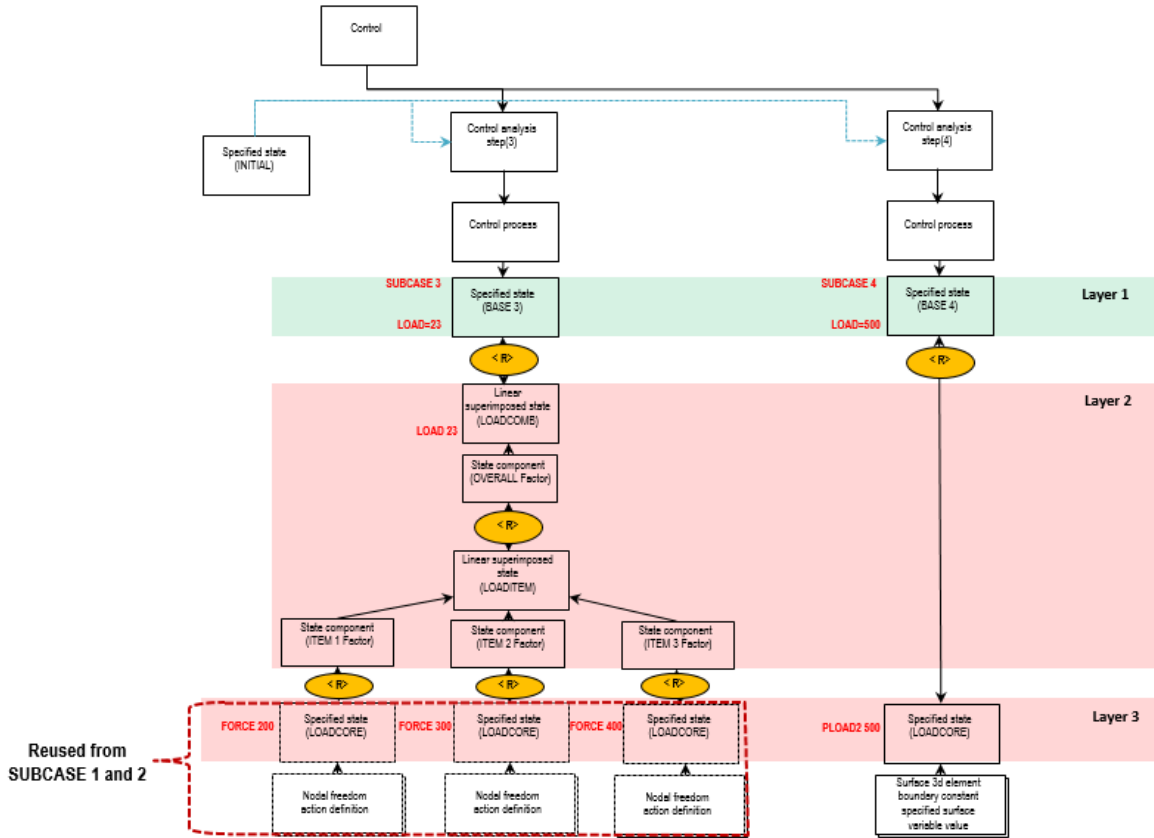


Figure 36 AT3 Applied Loads Subcase 3 and 4

As model size increases, the ability to make actual instance diagrams is quickly exceeded. Figure 37 demonstrates that even the simple AT2 bar model with three load cases and simple boundary conditions results in a complex diagram. However, it does illustrate the needed concepts.

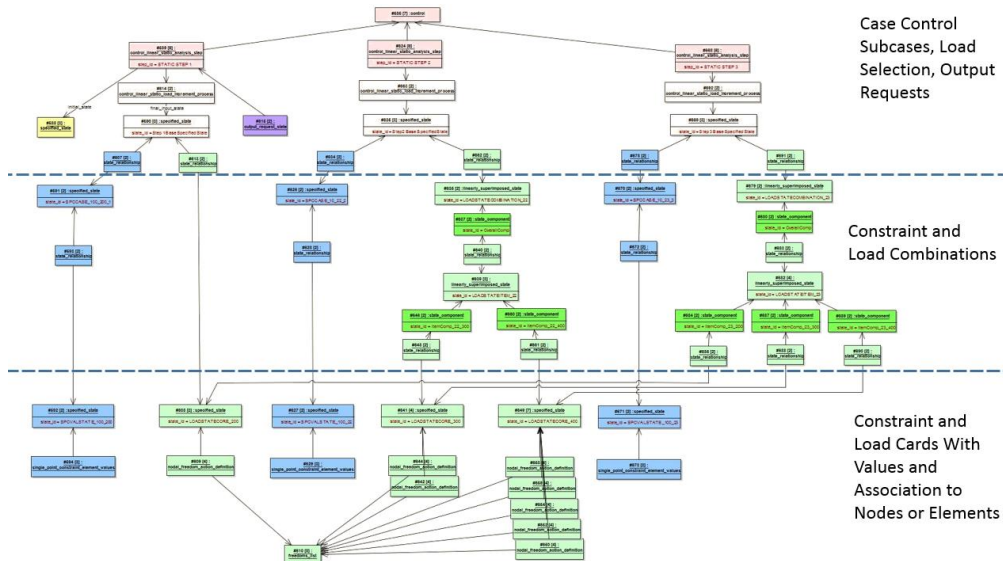


Figure 37 STEP Input Control Structures for AT2 CBAR Model

The instance diagram for subcase 3 of the ATS3 pilot study model is presented in Figure 38. This diagram corresponds to the NASTRAN information presented in Figure 23 and part of Figure 36.

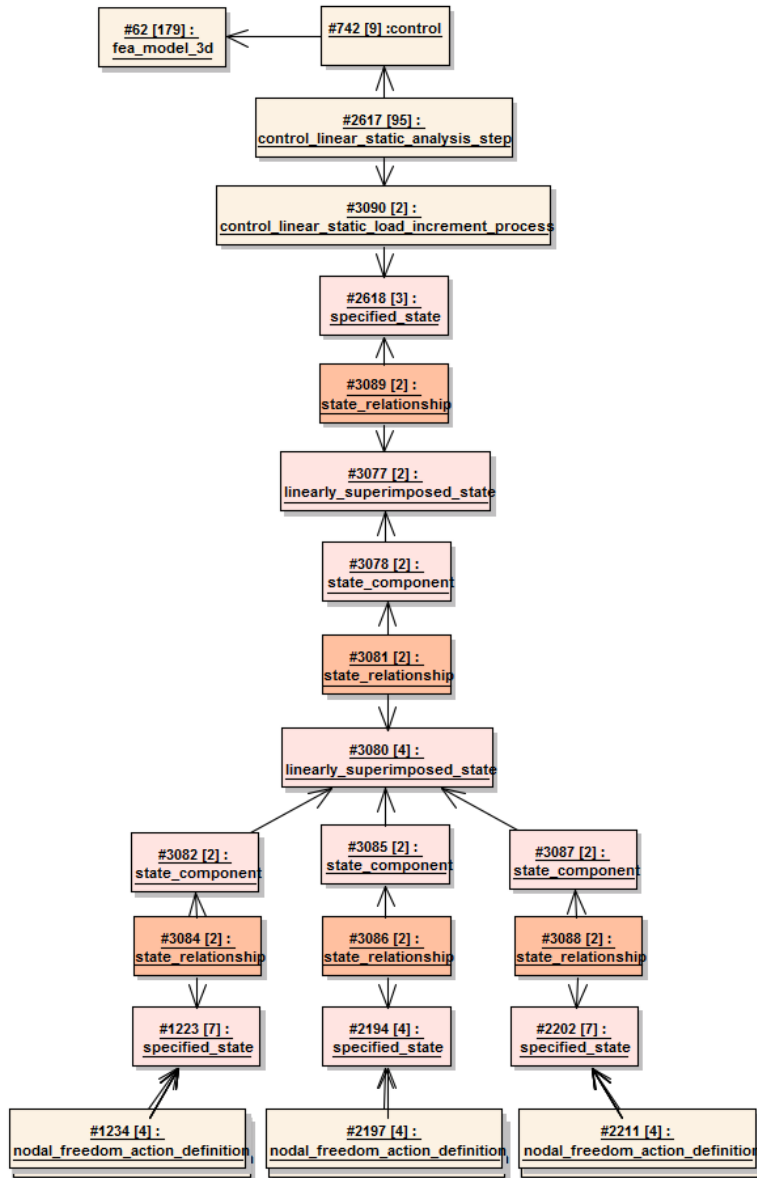


Figure 38 Instance Diagram for ATS3 Subcase 3

Lastly, the corresponding STEP file fragment is presented in Figure 39. One complete traversal from the **fea\_model\_3d** down to the **nodal\_freedom\_action\_definition**(s) of Figure 38 is shown. Only the **nodal\_freedom\_action\_definition**(s) from the lower left side of the figure are listed. The reader is referred to the Appendix B for the complete Part 21 listing.

```

#62= FEA_MODEL_3D('Identification',(#13),#28,
  'NASTRAN BDF Converter 0.0.0',('NASTRAN'),'AnalysisModelType');

#742= CONTROL(#62,'Control.0','FemConvert','Nastran job EAS test case ATS3m5',
  ('101','TIME 600','CEND','0','1','2','3','4','ENDDATA'),('NASTRAN'));
#2617= CONTROL_LINEAR_STATIC_ANALYSIS_STEP(#742,'STATIC STEP 3',3,#745,'',#3090);
#3090= CONTROL_LINEAR_STATIC_LOAD_INCREMENT_PROCESS('STATIC STEP 3','',#2618);

#2618= SPECIFIED_STATE('Step 3 Base Specified State','Relating Specified State');
#3089= STATE_RELATIONSHIP(
  'LOADSTATECOMBINATION_23 is related to Step 3 Base Specified State','',#2618,#3077);

#3077= LINEARLY_SUPERIMPOSED_STATE('23','Overall Factor Combined State');
#3078= STATE_COMPONENT('OverallComp','',#3077,1.);
#3081= STATE_RELATIONSHIP('LOADSTATEITEM_23 is related to OverallComp','',#3078,#3080);

#3080= LINEARLY_SUPERIMPOSED_STATE('LOADSTATEITEM_23','ItemComp Collector State');
#3082= STATE_COMPONENT('ItemComp_23_200','',#3080,1.);
#3085= STATE_COMPONENT('ItemComp_23_300','',#3080,1.);
#3087= STATE_COMPONENT('ItemComp_23_400','',#3080,1.);
#3084= STATE_RELATIONSHIP('LOADSTATECORE_200 is related to ItemComp_23_200','',#3082,#1223);
#3086= STATE_RELATIONSHIP('LOADSTATECORE_300 is related to ItemComp_23_300','',#3085,#2194);
#3088= STATE_RELATIONSHIP('LOADSTATECORE_400 is related to ItemComp_23_400','',#3087,#2202);

#1223= SPECIFIED_STATE('200','Core Loads Specified State');
#1224= NODAL_FREEDOM_ACTION_DEFINITION(#1223,#320,#13,#1225,(
  CONTEXT_DEPENDENT_MEASURE(-125.),CONTEXT_DEPENDENT_MEASURE(0.),CONTEXT_DEPENDENT_MEASURE(0.)),
  .APPLIED_LOADS.);
#1228= NODAL_FREEDOM_ACTION_DEFINITION(#1223,#344,#13,#1225,(
  CONTEXT_DEPENDENT_MEASURE(-250.),CONTEXT_DEPENDENT_MEASURE(0.),CONTEXT_DEPENDENT_MEASURE(0.)),
  .APPLIED_LOADS.);
#1230= NODAL_FREEDOM_ACTION_DEFINITION(#1223,#368,#13,#1225,(
  CONTEXT_DEPENDENT_MEASURE(-250.),CONTEXT_DEPENDENT_MEASURE(0.),CONTEXT_DEPENDENT_MEASURE(0.)),
  .APPLIED_LOADS.);
#1232= NODAL_FREEDOM_ACTION_DEFINITION(#1223,#392,#13,#1225,(
  CONTEXT_DEPENDENT_MEASURE(-250.),CONTEXT_DEPENDENT_MEASURE(0.),CONTEXT_DEPENDENT_MEASURE(0.)),
  .APPLIED_LOADS.);
#1234= NODAL_FREEDOM_ACTION_DEFINITION(#1223,#416,#13,#1225,(
  CONTEXT_DEPENDENT_MEASURE(-125.),CONTEXT_DEPENDENT_MEASURE(0.),CONTEXT_DEPENDENT_MEASURE(0.)),
  .APPLIED_LOADS.);

  <...state_definitions for Core load set 300 and 400 are similar and omitted...>

#1225= FREEDOMS_LIST(
  (ENUMERATED_DEGREE_OF_FREEDOM(.X_TRANSLATION.),
  ENUMERATED_DEGREE_OF_FREEDOM(.Y_TRANSLATION.),
  ENUMERATED_DEGREE_OF_FREEDOM(.Z_TRANSLATION.)));

#320= NODE('62',(#318),#28,#62);
#344= NODE('69',(#342),#28,#62);
#368= NODE('76',(#366),#28,#62);
#392= NODE('83',(#390),#28,#62);
#416= NODE('90',(#414),#28,#62);

```

Figure 39 STEP File Fragment for Applied Load Entities in for ATS3 Subcase 3



## 7 References and Links

This section provides a list of useful links the reader can use to learn more about the STEP standard, the US and European organizations that administer, develop and support these standards, and the LOTAR Engineering and Simulation Workgroup which authored this handbook in the frame of the CAE-IF.

The reader is encouraged to visit all the links for an introduction and overview of the activities of these organizations. However, the LOTAR EAS WG link and the CAx-IF and CAE-IF links contain reference material that is directly applicable to the topics discussed in the handbook.

LOTAR International	<a href="http://www.lotar-international.org">http://www.lotar-international.org</a>
LOTAR EAS WG	<a href="http://www.lotar-international.org/lotar-workgroups/engineering-analysis-simulation.html">http://www.lotar-international.org/lotar-workgroups/engineering-analysis-simulation.html</a>
NAFEMS	<a href="http://www.nafems.org">http://www.nafems.org</a>
AFNeT	<a href="http://www.afnet.fr">http://www.afnet.fr</a>
PDES, Inc.	<a href="https://www.pdesinc.org">https://www.pdesinc.org</a>
prostep ivip	<a href="http://www.prostep.org/en.html">http://www.prostep.org/en.html</a>
AIA	<a href="http://www.aia-aerospace.org">http://www.aia-aerospace.org</a>
ASD-STAN	<a href="http://www.asd-stan.org">http://www.asd-stan.org</a>
ISO STEP AP209 ed2	<a href="http://www.ap209.org">http://www.ap209.org</a>
CAx-IF	<a href="https://www.cax-if.org">https://www.cax-if.org</a>
CAE-IF	<a href="http://afnet.fr/dotank/sps/cae-if">http://afnet.fr/dotank/sps/cae-if</a>

*Table 2 Useful Links for Further Reading on ISO 10303-209 (STEP AP209)*

Table 3

## 8 Appendix A – NASTRAN Input File Full Listing

The NASTRAN input files for the four pilot models, as listed in the following four subsections, were used for this pilot study. They are not expected to be changed or updated unless a significant issue is identified that materially affects the generation of the STEP files. The first load case is defined consistently for all models with appropriate loads and boundary conditions to enable comparable solution data. However, the results will not be numerically identical due to differences in the model abstractions and element selection.

### 8.1 ATS1m5.bdf

```

$ Linear Static Analysis
SOL 101
TIME 600
CEND
$
SEALL = ALL
SUPER = ALL
TITLE = Nastran job EAS test case ATS1m5
ECHO = NONE
MAXLINES = 999999999
GPFORCE (PRINT,PUNCH) = ALL
$
SUBCASE 1
  SUBTITLE=subcase1 - axial load at tip
  SPC = 100
  LOAD = 200
  DISPLACEMENT (PRINT,PUNCH, SORT1, REAL)=ALL
  SPCFORCES (PRINT,PUNCH, SORT1, REAL)=ALL
  STRESS (PRINT,PUNCH, SORT1, REAL,VONMISES,BILIN)=ALL
  STRAIN (PRINT,PUNCH)=ALL
  FORCE (PRINT,PUNCH)=ALL
  ELSUM=ALL
$
BEGIN BULK
PARAM POST -1
PARAM AUTOSPC YES
PARAM NOCOMPS -1
PARAM PRTMAXIM YES
PARAM GRDPNT 0
$
PROD 1 1 8. 0.
$
CROD 1 1 1 2
CROD 2 1 2 3
CROD 3 1 3 4
CROD 4 1 4 5
CROD 5 1 5 6
CROD 6 1 6 7
CROD 7 1 7 8
CROD 8 1 8 9
CROD 9 1 9 10
CROD 10 1 10 11
CROD 11 1 11 12
CROD 12 1 12 13
CROD 13 1 13 14
CROD 14 1 14 15
CROD 15 1 15 16
CROD 16 1 16 17
$
MAT1 1 1.+.7 .33 2.54-4 1.3-5 70.
$
GRID 1 1 0. -2. 1.
GRID 2 1 1. -2. 1.
GRID 3 1 2. -2. 1.
GRID 4 1 3. -2. 1.
GRID 5 1 4. -2. 1.
GRID 6 1 5. -2. 1.
GRID 7 1 6. -2. 1.
GRID 8 1 7. -2. 1.
GRID 9 1 8. -2. 1.
GRID 10 1 9. -2. 1.

```

GRID	11	1	10.	-2.	1.			
GRID	12	1	11.	-2.	1.			
GRID	13	1	12.	-2.	1.			
GRID	14	1	13.	-2.	1.			
GRID	15	1	14.	-2.	1.			
GRID	16	1	15.	-2.	1.			
GRID	17	1	16.	-2.	1.			
\$								
SPC1	100	123	1					
\$								
FORCE	200	17	0	1000.	-1.	0.	0.	
\$								
CORD2R	1		0.	0.	0.	0.	0.	1.
	1.	0.	0.					
\$								
ENDDATA								

## 8.2 ATS2m5.bdf

```

$ Linear Static Analysis
SOL 101
TIME 600
CEND
$
SEALL = ALL
SUPER = ALL
TITLE = Nastran EAS test case ATS2m5
ECHO = NONE
MAXLINES = 999999999
GPFORCE (PRINT,PUNCH) = ALL
SUBCASE 1
  SUBTITLE=subcase1
  SPC = 100
  LOAD = 200
  DISPLACEMENT (PRINT,PUNCH, SORT1, REAL) =ALL
  SPCFORCES (PRINT,PUNCH, SORT1, REAL) =ALL
  STRESS (PRINT,PUNCH, SORT1, REAL, VONMISES, BILIN) =ALL
  STRAIN (PRINT,PUNCH) =ALL
  FORCE (PRINT,PUNCH) =ALL
  ELSUM=ALL
SUBCASE 2
  SUBTITLE=subcase2
  SPC = 10
  LOAD = 22
  DISPLACEMENT (PRINT,PUNCH, SORT1, REAL) =ALL
  SPCFORCES (PRINT,PUNCH, SORT1, REAL) =ALL
  STRESS (PRINT,PUNCH, SORT1, REAL, VONMISES, BILIN) =ALL
  STRAIN (PRINT,PUNCH) =ALL
  FORCE (PRINT,PUNCH) =ALL
SUBCASE 3
  SUBTITLE=subcase3
  SPC = 10
  LOAD = 23
  DISPLACEMENT (PRINT,PUNCH, SORT1, REAL) =ALL
  SPCFORCES (PRINT,PUNCH, SORT1, REAL, VONMISES, BILIN) =ALL
  STRAIN (PRINT,PUNCH) =ALL
  FORCE (PRINT,PUNCH) =ALL
$
BEGIN BULK
PARAM POST -1
PARAM AUTOSPC YES
PARAM NOCOMPS -1
PARAM PRTMAXIM YES
PARAM GRDPNT 0
$
PBAR 1 1 8. 2.667 10.667 0. 0.
     1. 2. 1. -2. -1. -2. -1. 2.
     0.
$
CBAR* 1 1 1 1 2
* 0. 7.54979-8 1.
CBAR* 2 1 2 3
* 0. 7.54979-8 1.
CBAR* 3 1 3 4
* 0. 7.54979-8 1.
CBAR* 4 1 4 5
* 0. 7.54979-8 1.
CBAR* 5 1 5 6
* 0. 7.54979-8 1.
CBAR* 6 1 6 7
* 0. 7.54979-8 1.
CBAR* 7 1 7 8
* 0. 7.54979-8 1.
CBAR* 8 1 8 9
* 0. 7.54979-8 1.
CBAR* 9 1 9 10
* 0. 7.54979-8 1.
CBAR* 10 1 10 11
* 0. 7.54979-8 1.
CBAR* 11 1 11 12
* 0. 7.54979-8 1.
CBAR* 12 1 12 13
* 0. 7.54979-8 1.
CBAR* 13 1 13 14
* 0. 7.54979-8 1.
CBAR* 14 1 14 15

```

```

*      0.      7.54979-8      1.
CBAR* 15      1      15      16
*      0.      7.54979-8      1.
CBAR* 16      1      16      17
*      0.      7.54979-8      1.
$
MAT1   1      1.+7      .33      2.54-4      1.3-5      70.
$
GRID  1      1      0.      -2.      1.
GRID  2      1      1.      -2.      1.
GRID  3      1      2.      -2.      1.
GRID  4      1      3.      -2.      1.
GRID  5      1      4.      -2.      1.
GRID  6      1      5.      -2.      1.
GRID  7      1      6.      -2.      1.
GRID  8      1      7.      -2.      1.
GRID  9      1      8.      -2.      1.
GRID 10      1      9.      -2.      1.
GRID 11      1      10.     -2.      1.
GRID 12      1      11.     -2.      1.
GRID 13      1      12.     -2.      1.
GRID 14      1      13.     -2.      1.
GRID 15      1      14.     -2.      1.
GRID 16      1      15.     -2.      1.
GRID 17      1      16.     -2.      1.
$
SPCADD 10      100
$
LOAD   22      1.      1.      300      1.      400
LOAD   23      1.      1.      200      1.      300      1.      400
$
SPC1   100      123456      1
$
FORCE  200      17      0      1000.     -1.      0.      0.
FORCE  300      11      0      10.        0.      -1.      0.
FORCE  300      17      0      10.        0.      -1.      0.
FORCE  400      12      0      20.        0.      -1.      0.
FORCE  400      13      0      20.        0.      -1.      0.
FORCE  400      14      0      20.        0.      -1.      0.
FORCE  400      15      0      20.        0.      -1.      0.
FORCE  400      16      0      20.        0.      -1.      0.
$
CORD2R 1      1.      0.      0.      0.      0.      0.      1.
1.      0.      0.
$
ENDDATA

```

### 8.3 ATS3m5.bdf

```

$ Linear Static Analysis
SOL 101
TIME 600
CEND
$
SEALL = ALL
SUPER = ALL
TITLE = Nastran job EAS test case ATS3m5
ECHO = NONE
MAXLINES = 999999999
GPFORCE (PRINT,PUNCH) = ALL
$
SUBCASE 1
  SUBTITLE=subcase1
  SPC = 11
  LOAD = 21
  DISPLACEMENT (PRINT, PUNCH, SORT1, REAL) =ALL
  SPCFORCES (PRINT, PUNCH, SORT1, REAL) =ALL
  STRESS (PRINT, PUNCH, SORT1, REAL, VONMISES, BILIN) =ALL
  STRAIN (PRINT, PUNCH, FIBER) =ALL
  FORCE (PRINT, PUNCH) =ALL
  ELSUM=ALL
SUBCASE 2
  SUBTITLE=subcase2
  SPC = 12
  LOAD = 22
  DISPLACEMENT (PRINT, PUNCH, SORT1, REAL) =ALL
  SPCFORCES (PRINT, PUNCH, SORT1, REAL) =ALL
  STRESS (PRINT, PUNCH, SORT1, REAL, VONMISES, BILIN) =ALL
  STRAIN (PRINT, PUNCH, FIBER) =ALL
  FORCE (PRINT, PUNCH) =ALL
SUBCASE 3
  SUBTITLE=subcase3
  SPC = 12
  LOAD = 23
  DISPLACEMENT (PRINT, PUNCH, SORT1, REAL) =ALL
  SPCFORCES (PRINT, PUNCH, SORT1, REAL) =ALL
  STRESS (PRINT, PUNCH, SORT1, REAL, VONMISES, BILIN) =ALL
  STRAIN (PRINT, PUNCH, FIBER) =ALL
  FORCE (PRINT, PUNCH) =ALL
SUBCASE 4
  SUBTITLE=subcase4
  SPC = 103
  LOAD = 500
  DISPLACEMENT (PRINT, PUNCH, SORT1, REAL) =ALL
  SPCFORCES (PRINT, PUNCH, SORT1, REAL) =ALL
  STRESS (PRINT, PUNCH, SORT1, REAL, VONMISES, BILIN) =ALL
  STRAIN (PRINT, PUNCH, FIBER) =ALL
  FORCE (PRINT, PUNCH) =ALL
$
BEGIN BULK
PARAM   POST      -1
PARAM   AUTOSPC   YES
PARAM   NOCOMPS   -1
PARAM   PRTMAXIM  YES
PARAM   GRDPNT    0
$
PSHELL  1      1      2.      1      1
$
CQUAD4  1      1      1      2      13      12
CQUAD4  2      1      2      3      14      13
CQUAD4  3      1      3      4      15      14
CQUAD4  4      1      4      5      16      15
CQUAD4  5      1      5      6      17      16
CQUAD4  6      1      6      7      18      17
CQUAD4  7      1      7      8      19      18
CQUAD4  8      1      8      9      20      19
CQUAD4  9      1      9      10     21      20
CQUAD4  10     1      10     11     22      21
CQUAD4  11     1      12     13     24      23
CQUAD4  12     1      13     14     25      24
CQUAD4  13     1      14     15     26      25
CQUAD4  14     1      15     16     27      26
CQUAD4  15     1      16     17     28      27
CQUAD4  16     1      17     18     29      28
CQUAD4  17     1      18     19     30      29
CQUAD4  18     1      19     20     31      30
CQUAD4  19     1      20     21     32      31

```

CQUAD4	20	1	21	22	33	32
CQUAD4	21	1	23	24	35	34
CQUAD4	22	1	24	25	36	35
CQUAD4	23	1	25	26	37	36
CQUAD4	24	1	26	27	38	37
CQUAD4	25	1	27	28	39	38
CQUAD4	26	1	28	29	40	39
CQUAD4	27	1	29	30	41	40
CQUAD4	28	1	30	31	42	41
CQUAD4	29	1	31	32	43	42
CQUAD4	30	1	32	33	44	43
CQUAD4	31	1	34	35	46	45
CQUAD4	32	1	35	36	47	46
CQUAD4	33	1	36	37	48	47
CQUAD4	34	1	37	38	49	48
CQUAD4	35	1	38	39	50	49
CQUAD4	36	1	39	40	51	50
CQUAD4	37	1	40	41	52	51
CQUAD4	38	1	41	42	53	52
CQUAD4	39	1	42	43	54	53
CQUAD4	40	1	43	44	55	54
CTRIA3	41	1	64	22	11	
CTRIA3	42	1	11	57	64	
CTRIA3	43	1	57	58	64	
CTRIA3	44	1	65	64	58	
CTRIA3	45	1	66	65	58	
CTRIA3	46	1	58	59	66	
CTRIA3	47	1	59	60	66	
CTRIA3	48	1	67	66	60	
CTRIA3	49	1	68	67	60	
CTRIA3	50	1	60	61	68	
CTRIA3	51	1	61	62	68	
CTRIA3	52	1	69	68	62	
CTRIA3	53	1	22	64	33	
CTRIA3	54	1	71	33	64	
CTRIA3	55	1	72	71	64	
CTRIA3	56	1	64	65	72	
CTRIA3	57	1	65	66	72	
CTRIA3	58	1	73	72	66	
CTRIA3	59	1	74	73	66	
CTRIA3	60	1	66	67	74	
CTRIA3	61	1	67	68	74	
CTRIA3	62	1	75	74	68	
CTRIA3	63	1	76	75	68	
CTRIA3	64	1	68	69	76	
CTRIA3	65	1	78	44	33	
CTRIA3	66	1	33	71	78	
CTRIA3	67	1	71	72	78	
CTRIA3	68	1	79	78	72	
CTRIA3	69	1	80	79	72	
CTRIA3	70	1	72	73	80	
CTRIA3	71	1	73	74	80	
CTRIA3	72	1	81	80	74	
CTRIA3	73	1	82	81	74	
CTRIA3	74	1	74	75	82	
CTRIA3	75	1	75	76	82	
CTRIA3	76	1	83	82	76	
CTRIA3	77	1	44	78	55	
CTRIA3	78	1	85	55	78	
CTRIA3	79	1	86	85	78	
CTRIA3	80	1	78	79	86	
CTRIA3	81	1	79	80	86	
CTRIA3	82	1	87	86	80	
CTRIA3	83	1	88	87	80	
CTRIA3	84	1	80	81	88	
CTRIA3	85	1	81	82	88	
CTRIA3	86	1	89	88	82	
CTRIA3	87	1	90	89	82	
CTRIA3	88	1	82	83	90	
\$						
MAT1	1	1.+7		.33	2.54-4	1.3-5 70.
\$						
GRID*	1				-6.24022-8	-4.
*	1.					
GRID	2		1.	-4.	1.	
GRID	3		2.	-4.	1.	
GRID	4		3.	-4.	1.	
GRID	5		4.	-4.	1.	
GRID	6		5.	-4.	1.	
GRID	7		6.	-4.	1.	
GRID	8		7.	-4.	1.	
GRID	9		8.	-4.	1.	

GRID	10	9.	-4.	1.		
GRID	11	10.	-4.	1.		
GRID*	12				-6.24022-8	-3.
*	1.					
GRID	13	1.	-3.	1.		
GRID	14	2.	-3.	1.		
GRID	15	3.	-3.	1.		
GRID	16	4.	-3.	1.		
GRID	17	5.	-3.	1.		
GRID	18	6.	-3.	1.		
GRID	19	7.	-3.	1.		
GRID	20	8.	-3.	1.		
GRID	21	9.	-3.	1.		
GRID	22	10.	-3.	1.		
GRID*	23				-6.24022-8	-2.
*	1.					
GRID	24	1.	-2.	1.		
GRID	25	2.	-2.	1.		
GRID	26	3.	-2.	1.		
GRID	27	4.	-2.	1.		
GRID	28	5.	-2.	1.		
GRID	29	6.	-2.	1.		
GRID	30	7.	-2.	1.		
GRID	31	8.	-2.	1.		
GRID	32	9.	-2.	1.		
GRID	33	10.	-2.	1.		
GRID*	34				-6.24022-8	-1.
*	1.					
GRID	35	1.	-1.	1.		
GRID	36	2.	-1.	1.		
GRID	37	3.	-1.	1.		
GRID	38	4.	-1.	1.		
GRID	39	5.	-1.	1.		
GRID	40	6.	-1.	1.		
GRID	41	7.	-1.	1.		
GRID	42	8.	-1.	1.		
GRID	43	9.	-1.	1.		
GRID	44	10.	-1.	1.		
GRID*	45				-6.24022-8	-5.27577-8
*	1.					
GRID*	46				1.	-5.27577-8
*	1.					
GRID*	47				2.	-5.27577-8
*	1.					
GRID*	48				3.	-5.27577-8
*	1.					
GRID*	49				4.	-5.27577-8
*	1.					
GRID*	50				5.	-5.27577-8
*	1.					
GRID*	51				6.	-5.27577-8
*	1.					
GRID*	52				7.	-5.27577-8
*	1.					
GRID*	53				8.	-5.27577-8
*	1.					
GRID*	54				9.	-5.27577-8
*	1.					
GRID*	55				10.	-5.27577-8
*	1.					
GRID	57	11.	-4.	1.		
GRID	58	12.	-4.	1.		
GRID	59	13.	-4.	1.		
GRID	60	14.	-4.	1.		
GRID	61	15.	-4.	1.		
GRID	62	16.	-4.	1.		
GRID	64	11.	-3.	1.		
GRID	65	12.	-3.	1.		
GRID	66	13.	-3.	1.		
GRID	67	14.	-3.	1.		
GRID	68	15.	-3.	1.		
GRID	69	16.	-3.	1.		
GRID	71	11.	-2.	1.		
GRID	72	12.	-2.	1.		
GRID	73	13.	-2.	1.		
GRID	74	14.	-2.	1.		
GRID	75	15.	-2.	1.		
GRID	76	16.	-2.	1.		
GRID	78	11.	-1.	1.		
GRID	79	12.	-1.	1.		
GRID	80	13.	-1.	1.		
GRID	81	14.	-1.	1.		



GRID	82		15.	-1.	1.			
GRID	83		16.	-1.	1.			
GRID*	85				11.			-5.27577-8
*	1.							
GRID*	86				12.			-5.27577-8
*	1.							
GRID*	87				13.			-5.27577-8
*	1.							
GRID*	88				14.			-5.27577-8
*	1.							
GRID*	89				15.			-5.27577-8
*	1.							
GRID*	90				16.			-5.27577-8
*	1.							
\$								
SPCADD	11	100	101	110				
SPCADD	12	100	102	110				
\$								
LOAD	21	1.	1.	200				
LOAD	22	1.	1.	300	1.	400		
LOAD	23	1.	1.	200	1.	300	1.	400
\$								
SPC1	100	123	23					
SPC1	101	1	1	12	34	45		
SPC1	102	123	1	12	34	45		
SPC1	103	123	23					
SPC1	103	23	76					
SPC1	103	3	1	12	34	45		
SPC1	103	3	62	69	83	90		
SPC1	110	45	1	THRU	55			
SPC1	110	45	57	58	59	60	61	62
	64	65	66	67	68	69	71	72
	73	74	75	76	78	79	80	81
	82	83	85	86	87	88	89	90
\$								
FORCE	200	62	0	125.	-1.	0.	0.	
FORCE	200	69	0	250.	-1.	0.	0.	
FORCE	200	76	0	250.	-1.	0.	0.	
FORCE	200	83	0	250.	-1.	0.	0.	
FORCE	200	90	0	125.	-1.	0.	0.	
FORCE	300	55	0	10.	0.	-1.	0.	
FORCE	300	90	0	10.	0.	-1.	0.	
FORCE	400	85	0	20.	0.	-1.	0.	
FORCE	400	86	0	20.	0.	-1.	0.	
FORCE	400	87	0	20.	0.	-1.	0.	
FORCE	400	88	0	20.	0.	-1.	0.	
FORCE	400	89	0	20.	0.	-1.	0.	
\$								
PLOAD2		500-125.0		8				
PLOAD2		500-125.0		9				
PLOAD2		500-125.0		18				
PLOAD2		500-125.0		19				
PLOAD2		500-125.0		28				
PLOAD2		500-125.0		29				
PLOAD2		500-125.0		38				
PLOAD2		500-125.0		39				
\$								
ENDDATA								

## 8.4 ATS4m5.bdf

```

$ Linear Static Analysis
SOL 101
TIME 600
CEND
$
SEALL = ALL
SUPER = ALL
TITLE = Nastran job EAS test case ATS4m5
ECHO = NONE
MAXLINES = 999999999
GPFORCE (PRINT,PUNCH) = ALL
$
SUBCASE 1
  SUBTITLE=subcase1
  SPC = 11
  LOAD = 21
  DISPLACEMENT (PRINT,PUNCH, SORT1, REAL)=ALL
  SPCFORCES (PRINT,PUNCH, SORT1, REAL)=ALL
  STRESS (PRINT,PUNCH, SORT1, REAL,VONMISES, BILIN)=ALL
  STRAIN (PRINT,PUNCH)=ALL
  FORCE (PRINT,PUNCH)=ALL
  ELSUM=ALL
SUBCASE 2
  SUBTITLE=subcase2
  SPC = 12
  LOAD = 22
  DISPLACEMENT (PRINT,PUNCH, SORT1, REAL)=ALL
  SPCFORCES (PRINT,PUNCH, SORT1, REAL)=ALL
  STRESS (PRINT,PUNCH, SORT1, REAL,VONMISES, BILIN)=ALL
  STRAIN (PRINT,PUNCH)=ALL
  FORCE (PRINT,PUNCH)=ALL
SUBCASE 3
  SUBTITLE=subcase3
  SPC = 12
  LOAD = 23
  DISPLACEMENT (PRINT,PUNCH, SORT1, REAL)=ALL
  SPCFORCES (PRINT,PUNCH, SORT1, REAL)=ALL
  STRESS (PRINT,PUNCH, SORT1, REAL,VONMISES, BILIN)=ALL
  STRAIN (PRINT,PUNCH)=ALL
  FORCE (PRINT,PUNCH)=ALL
$
BEGIN BULK
PARAM  POST      -1
PARAM  AUTOSPC   YES
PARAM  PRTMAXIM  YES
PARAM  GRDPNT    0
$
PSOLID  1      1      0
$
CHEXA  1      1      1      2      7      6      16      17
      22      21
CHEXA  2      1      2      3      8      7      17      18
      23      22
CHEXA  3      1      3      4      9      8      18      19
      24      23
CHEXA  4      1      4      5      10     9      19      20
      25      24
CHEXA  5      1      6      7      12     11     21      22
      27      26
CHEXA  6      1      7      8      13     12     22      23
      28      27
CHEXA  7      1      8      9      14     13     23      24
      29      28
CHEXA  8      1      9      10     15     14     24      25
      30      29
CHEXA  9      1      16     17     22     21     31      32
      37      36
CHEXA  10     1      17     18     23     22     32      33
      38      37
CHEXA  11     1      18     19     24     23     33      34
      39      38
CHEXA  12     1      19     20     25     24     34      35
      40      39
CHEXA  13     1      21     22     27     26     36      37
      42      41
CHEXA  14     1      22     23     28     27     37      38
      43      42
CHEXA  15     1      23     24     29     28     38      39

```

	44	43						
CHEXA	16	1	24	25	30	29	39	40
	45	44						
CHEXA	17	1	31	32	37	36	46	47
	52	51						
CHEXA	18	1	32	33	38	37	47	48
	53	52						
CHEXA	19	1	33	34	39	38	48	49
	54	53						
CHEXA	20	1	34	35	40	39	49	50
	55	54						
CHEXA	21	1	36	37	42	41	51	52
	57	56						
CHEXA	22	1	37	38	43	42	52	53
	58	57						
CHEXA	23	1	38	39	44	43	53	54
	59	58						
CHEXA	24	1	39	40	45	44	54	55
	60	59						
CHEXA	25	1	46	47	52	51	61	62
	67	66						
CHEXA	26	1	47	48	53	52	62	63
	68	67						
CHEXA	27	1	48	49	54	53	63	64
	69	68						
CHEXA	28	1	49	50	55	54	64	65
	70	69						
CHEXA	29	1	51	52	57	56	66	67
	72	71						
CHEXA	30	1	52	53	58	57	67	68
	73	72						
CHEXA	31	1	53	54	59	58	68	69
	74	73						
CHEXA	32	1	54	55	60	59	69	70
	75	74						
\$								
CTETRA	33	1	76	83	111	77		
CTETRA	34	1	118	111	83	119		
CTETRA	35	1	84	77	119	83		
CTETRA	36	1	112	119	77	111		
CTETRA	37	1	77	83	111	119		
CTETRA	38	1	84	119	77	85		
CTETRA	39	1	112	77	119	113		
CTETRA	40	1	78	113	85	77		
CTETRA	41	1	120	85	113	119		
CTETRA	42	1	77	85	119	113		
CTETRA	43	1	78	85	113	79		
CTETRA	44	1	120	113	85	121		
CTETRA	45	1	86	79	121	85		
CTETRA	46	1	114	121	79	113		
CTETRA	47	1	79	85	113	121		
CTETRA	48	1	86	121	79	87		
CTETRA	49	1	114	79	121	115		
CTETRA	50	1	80	115	87	79		
CTETRA	51	1	122	87	115	121		
CTETRA	52	1	79	87	121	115		
CTETRA	53	1	80	87	115	81		
CTETRA	54	1	122	115	87	123		
CTETRA	55	1	88	81	123	87		
CTETRA	56	1	116	123	81	115		
CTETRA	57	1	81	87	115	123		
CTETRA	58	1	88	123	81	64		
CTETRA	59	1	116	81	123	70		
CTETRA	60	1	65	70	64	81		
CTETRA	61	1	69	64	70	123		
CTETRA	62	1	81	64	123	70		
CTETRA	63	1	90	125	83	91		
CTETRA	64	1	118	83	125	119		
CTETRA	65	1	84	119	91	83		
CTETRA	66	1	126	91	119	125		
CTETRA	67	1	83	91	125	119		
CTETRA	68	1	84	91	119	85		
CTETRA	69	1	126	119	91	127		
CTETRA	70	1	92	85	127	91		
CTETRA	71	1	120	127	85	119		
CTETRA	72	1	85	91	119	127		
CTETRA	73	1	92	127	85	93		
CTETRA	74	1	120	85	127	121		
CTETRA	75	1	86	121	93	85		
CTETRA	76	1	128	93	121	127		
CTETRA	77	1	85	93	127	121		
CTETRA	78	1	86	93	121	87		

CTETRA	79	1	128	121	93	129
CTETRA	80	1	94	87	129	93
CTETRA	81	1	122	129	87	121
CTETRA	82	1	87	93	121	129
CTETRA	83	1	94	129	87	95
CTETRA	84	1	122	87	129	123
CTETRA	85	1	88	123	95	87
CTETRA	86	1	130	95	123	129
CTETRA	87	1	87	95	129	123
CTETRA	88	1	88	95	123	64
CTETRA	89	1	130	123	95	68
CTETRA	90	1	63	64	68	95
CTETRA	91	1	69	68	64	123
CTETRA	92	1	64	95	123	68
CTETRA	93	1	90	97	125	91
CTETRA	94	1	132	125	97	133
CTETRA	95	1	98	91	133	97
CTETRA	96	1	126	133	91	125
CTETRA	97	1	91	97	125	133
CTETRA	98	1	98	133	91	99
CTETRA	99	1	126	91	133	127
CTETRA	100	1	92	127	99	91
CTETRA	101	1	134	99	127	133
CTETRA	102	1	91	99	133	127
CTETRA	103	1	92	99	127	93
CTETRA	104	1	134	127	99	135
CTETRA	105	1	100	93	135	99
CTETRA	106	1	128	135	93	127
CTETRA	107	1	93	99	127	135
CTETRA	108	1	100	135	93	101
CTETRA	109	1	128	93	135	129
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CPENTA	367	1	139	249	242	174	284	277
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GRID	174	10.	-4.	2.	
GRID	175	9.	-4.	2.	
GRID	176	8.	-4.	2.	
GRID	177	7.	-4.	2.	
GRID	178	6.	-4.	2.	
GRID	179	5.	-4.	2.	
GRID*	181			16.	-5.27577-8
*	0.				
GRID*	182			15.	-5.27577-8
*	0.				
GRID*	183			14.	-5.27577-8
*	0.				
GRID*	184			13.	-5.27577-8
*	0.				
GRID*	185			12.	-5.27577-8
*	0.				
GRID*	186			11.	-5.27577-8
*	0.				
GRID	188	16.	-1.	0.	
GRID	189	15.	-1.	0.	
GRID	190	14.	-1.	0.	
GRID	191	13.	-1.	0.	
GRID	192	12.	-1.	0.	
GRID	193	11.	-1.	0.	
GRID	195	16.	-2.	0.	
GRID	196	15.	-2.	0.	
GRID	197	14.	-2.	0.	
GRID	198	13.	-2.	0.	
GRID	199	12.	-2.	0.	
GRID	200	11.	-2.	0.	
GRID	202	16.	-3.	0.	
GRID	203	15.	-3.	0.	
GRID	204	14.	-3.	0.	
GRID	205	13.	-3.	0.	
GRID	206	12.	-3.	0.	
GRID	207	11.	-3.	0.	
GRID	209	16.	-4.	0.	
GRID	210	15.	-4.	0.	
GRID	211	14.	-4.	0.	
GRID	212	13.	-4.	0.	
GRID	213	12.	-4.	0.	
GRID	214	11.	-4.	0.	
GRID*	216			16.	-5.27577-8
*	1.				
GRID*	217			15.	-5.27577-8
*	1.				
GRID*	218			14.	-5.27577-8
*	1.				
GRID*	219			13.	-5.27577-8
*	1.				
GRID*	220			12.	-5.27577-8
*	1.				
GRID*	221			11.	-5.27577-8
*	1.				
GRID	223	16.	-1.	1.	
GRID	224	15.	-1.	1.	
GRID	225	14.	-1.	1.	
GRID	226	13.	-1.	1.	
GRID	227	12.	-1.	1.	
GRID	228	11.	-1.	1.	
GRID	230	16.	-2.	1.	
GRID	231	15.	-2.	1.	
GRID	232	14.	-2.	1.	
GRID	233	13.	-2.	1.	
GRID	234	12.	-2.	1.	
GRID	235	11.	-2.	1.	
GRID	237	16.	-3.	1.	
GRID	238	15.	-3.	1.	

GRID	239		14.	-3.	1.				
GRID	240		13.	-3.	1.				
GRID	241		12.	-3.	1.				
GRID	242		11.	-3.	1.				
GRID	244		16.	-4.	1.				
GRID	245		15.	-4.	1.				
GRID	246		14.	-4.	1.				
GRID	247		13.	-4.	1.				
GRID	248		12.	-4.	1.				
GRID	249		11.	-4.	1.				
GRID*	251				16.				-5.27577-8
*	2.								
GRID*	252				15.				-5.27577-8
*	2.								
GRID*	253				14.				-5.27577-8
*	2.								
GRID*	254				13.				-5.27577-8
*	2.								
GRID*	255				12.				-5.27577-8
*	2.								
GRID*	256				11.				-5.27577-8
*	2.								
GRID	258		16.	-1.	2.				
GRID	259		15.	-1.	2.				
GRID	260		14.	-1.	2.				
GRID	261		13.	-1.	2.				
GRID	262		12.	-1.	2.				
GRID	263		11.	-1.	2.				
GRID	265		16.	-2.	2.				
GRID	266		15.	-2.	2.				
GRID	267		14.	-2.	2.				
GRID	268		13.	-2.	2.				
GRID	269		12.	-2.	2.				
GRID	270		11.	-2.	2.				
GRID	272		16.	-3.	2.				
GRID	273		15.	-3.	2.				
GRID	274		14.	-3.	2.				
GRID	275		13.	-3.	2.				
GRID	276		12.	-3.	2.				
GRID	277		11.	-3.	2.				
GRID	279		16.	-4.	2.				
GRID	280		15.	-4.	2.				
GRID	281		14.	-4.	2.				
GRID	282		13.	-4.	2.				
GRID	283		12.	-4.	2.				
GRID	284		11.	-4.	2.				
\$									
SPCADD	11	100	101						
SPCADD	12	100	102						
\$									
LOAD	21	1.	1.	200					
LOAD	22	1.	1.	300	1.	400			
LOAD	23	1.	1.	200	1.	300	1.	400	
\$									
SPC1	100	123	8						
SPC1	100	3	6						
SPC1	101	1	1	THRU	7				
SPC1	101	1	9	THRU	15				
SPC1	102	123	1	THRU	7				
SPC1	102	123	9	THRU	15				
\$									
FORCE	200	181	0	31.25	-1.	0.	0.		
FORCE	200	209	0	31.25	-1.	0.	0.		
FORCE	200	251	0	31.25	-1.	0.	0.		
FORCE	200	279	0	31.25	-1.	0.	0.		
FORCE	200	188	0	62.50	-1.	0.	0.		
FORCE	200	195	0	62.50	-1.	0.	0.		
FORCE	200	202	0	62.50	-1.	0.	0.		
FORCE	200	216	0	62.50	-1.	0.	0.		
FORCE	200	244	0	62.50	-1.	0.	0.		
FORCE	200	258	0	62.50	-1.	0.	0.		
FORCE	200	265	0	62.50	-1.	0.	0.		
FORCE	200	272	0	62.50	-1.	0.	0.		
FORCE	200	223	0	125.0	-1.	0.	0.		
FORCE	200	230	0	125.0	-1.	0.	0.		
FORCE	200	237	0	125.0	-1.	0.	0.		
FORCE	300	76		01.0	0.0	-2.5	0.0		
FORCE	300	146		01.0	0.0	-2.5	0.0		
FORCE	300	181		01.0	0.0	-2.5	0.0		
FORCE	300	251		01.0	0.0	-2.5	0.0		
FORCE	300	111		01.0	0.0	-5.0	0.0		
FORCE	300	186		01.0	0.0	-5.0	0.0		

FORCE	300	183	01.0	0.0	-5.0	0.0
FORCE	300	184	01.0	0.0	-5.0	0.0
FORCE	300	185	01.0	0.0	-5.0	0.0
FORCE	300	182	01.0	0.0	-5.0	0.0
FORCE	300	216	01.0	0.0	-5.0	0.0
FORCE	300	252	01.0	0.0	-5.0	0.0
FORCE	300	253	01.0	0.0	-5.0	0.0
FORCE	300	254	01.0	0.0	-5.0	0.0
FORCE	300	255	01.0	0.0	-5.0	0.0
FORCE	300	256	01.0	0.0	-5.0	0.0
FORCE	400	217	01.0	0.0	-10.0	0.0
FORCE	400	218	01.0	0.0	-10.0	0.0
FORCE	400	219	01.0	0.0	-10.0	0.0
FORCE	400	220	01.0	0.0	-10.0	0.0
FORCE	400	221	01.0	0.0	-10.0	0.0
\$						
ENDDATA						

## 9 Appendix B – STEP Part21 Output File Full Listing

The following are links to the full STEP Part21 file contents for the 4 pilot models. This section will be updated as the STEP converters mature and required corrections are incorporated into this document. As such, the actual instance identifiers in these files may not match the ones used in the figures and tables within the body of this document.

### 9.1 ATS1m4.stp

<Link available at the CAE-IF>

### 9.2 ATS2m4.stp

<Link available at the CAE-IF>

### 9.3 ATS3m4.stp

<Link available at the CAE-IF>

### 9.4 ATS4m4.stp

<Link available at the CAE-IF>

END OF DOCUMENT